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## Citation:

J. de Vries, Involutions in a field of circles, in:

KNAW, Proceedings, 22 I, 1919-1920, Amsterdam, 1919, pp. 379-382

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Mathematics. - "Involutions in a field of circles". By Prof. Jan de Vries.
(Communicated in the meeting of September 27, 1919).

1. In a plane are given three systems of coaxial circles $(\boldsymbol{\alpha}),(\beta),(\gamma)$ in each of which the circles are arranged in the pairs $\alpha_{1}, \alpha_{2}$ etc. of an involution. Let $\delta_{1}$ be the circle which intersects the circles $\alpha_{1}, \beta_{1}, \gamma_{1}$ orthogonally, $\delta_{2}$ the orthogonal circle of the corresponding circles $\alpha_{2}, \beta_{2}, \gamma_{2}$, then $\delta_{1}$ and $\delta_{2}$ are conjugated in an molutory correspondence in the field of circles.

Since $\alpha_{1}$ coincides twice with $\alpha_{2}, \beta_{1}$ twice with $\beta_{2}$ and $\gamma_{1}$ twice with $\gamma_{2}$, the involution $\left(\delta_{1}, \delta_{2}\right)$ has eight coincidences.

In general an arbitrary circle $\delta_{1}$ is intersected orthogonally by one circle $a$ only. However, when $\delta_{1}$ belongs to the system ( $a^{\prime}$ ) of coaxial circles orthogonally intersecting the circles of $(\alpha)$ then $\alpha_{1}$, and $\alpha_{2}$ also, is an arbitrary circle from ( $\alpha$ ), whilst $\beta_{2}$ and $\gamma_{2}$ are perfectly defined. In this case every circle $\delta_{2}$ intersecting $\beta_{2}$ and $\gamma_{2}$ orthogonally corresponds with $\boldsymbol{\delta}_{1}$.

Hence the orthogonal systems $\left(\alpha^{\prime}\right),\left(\beta^{\prime}\right),\left(\gamma^{\prime}\right)$ of $(\alpha),(\beta),(\gamma)$ consist of singular circles, i.e. of circles which in the involution are conjugated each to an infinite number of circles.

There is still another way in which $\delta_{1}$ may be singular. On a circle $\alpha$ the systems ( $\beta$ ) and ( $\gamma$ ) determine two involutions; since these have one pair in common, on $\alpha$ are to be found the two points of intersection of a circle $\beta$ with a circle $\gamma$. Hence every circle $\alpha$ (or $\beta$, or $\gamma$ ) belongs to a triplet $\alpha_{2}, \beta_{2}, \gamma_{2}$, belonging to one system of circles and for which the orthogonal circle accordingly becomes indefinite. The circle $\delta_{1}$ which intersects the corresponding circles $\alpha_{1}, \beta_{1}, \gamma_{1}$ orthogonally is therefore singular and conjugated to every circle of a certain system of coaxial circles.
2. A further investigation of the involution ( $\delta_{1}, \delta_{2}$ ) becomes comparatively simple, when we make use of a representation of the circles of the field on the points of space, to which Dr. K. W. Walstra has attracted attention in $1917^{1}$ ).

In order to obtain this representation we take the plane of our circles as the plane of coordinales $z=0$. A circle we then represent

[^0]by the point on its axis with coordinate $z$ equal to the power of the origin $O$ with respect to the circle

All circles with radius zero are represented by the points of a paraboloid of revolution $\mathbf{G}$ (limiting surface) and the images of two orthogonal circles are harmonically separated by $\mathbf{G}$. Two reciprocal polar lines are the images of two systems of coaxial circles orthogonal to each other.

The systems $(\alpha),(\beta),(\gamma)$ are represented by three involutions $\left(A_{1}, A_{2}\right),\left(B_{1}, B_{2}\right),\left(C_{1}, C_{2}\right)$ situated on three straight lines $a, b, c$. The image $D_{1}$ of the circle $\delta_{1}$, which intersects $\alpha_{1}, \beta_{1}, \gamma_{1}$ orthogonally is the pole of the plane $A_{1} B_{1} C_{1}$. So we have now to consider an involution ( $D_{1}, D_{2}$ ) of the points of space, which involution is characterized by the property that the polar planes $\Delta_{1}$ and $\Delta_{2}$ of $D_{1}$ and $D_{2}$ meet the given lines $a, b, c$ in the pairs $\left(A_{1}, A_{2}\right),\left(B_{1}, B_{2}\right)$, $\left(C_{1}, C_{2}\right)$ of three given involutions.
3. It is now easy to find the singular elements of the involution of circles again. In the first place we observe that $A_{1}$ becomes indefinite as soon as $\Delta_{1}$ passes through $a$; for $\Delta_{\text {, now any plane }}$ may be chosen which contains the points $B_{2}$ and $C_{2}$, hence for $D_{2}$ any point of the polar line $a^{\prime}$; of the straight line $a_{2} \equiv B_{2} C_{3}$. If $\Delta_{1}$ is made to revolve about $a$, then $D_{1}$ moves along the polar line $a^{\prime}$ of $a$, and $a_{2}$ describes a ruled quadric. The line $a_{2}^{\prime}$ also describes a ruled quadric $\left(a_{2}^{\prime}\right)^{2}$ of which the polar lines $b^{\prime}$ and $c^{\prime}$ of $b$ and $c$ are directrices. It is obvious that to every point of $a^{\prime}$ a definite straight line of $\left(a_{2}^{\prime}\right)^{1}$ is conjugated. Similarly to the singular lines $b^{\prime}, c^{\prime}$ correspond the ruled quadrics $\left(b_{2}^{\prime}\right)^{2},\left(c_{2}^{\prime}\right)^{2}$.

Secondly $D_{2}$ becomes indefinite as soon as $A_{2}, B_{2}$ and $C_{2}$ are collinear and therefore situated on a transversal $s$ of $a, b, c$. When $s$ is made to coincide successively with the generators of the ruled quadric having $a, b, c$ for directrices, then $A_{1}, B_{1}$ and $C_{1}$ describe three projective ranges, so that $\triangle_{1}$ osculates a twisted cabic $\sigma^{2}$, of which the lines $a^{\prime}, b^{\prime}$ and $c^{\prime}$ are bisecants. To every point $S \equiv D_{1}$ of this singular curve $\sigma^{2}$ evidently is correlated a line $s^{\prime}$ viz. the polar line of the corresponding line $s$. The lines $s^{\prime}$ form a ruled quadric $\left(s^{\prime}\right)^{2}$ with the directrices $\alpha^{\prime}, b^{\prime}, c^{\prime}$.
4. If $D_{1}$ describes the line $l$, then $\triangle_{1}$ revolves about the polar line $l^{\prime}$, so that $A_{1}, B_{1}$ and $C_{1}$ describe projective ranges. $A_{2}, B_{2}$ and $C$, then also describe projective ranges; hence $\Delta$, osculates a twisted cubic $\lambda^{3}$, of which $a^{\prime}, b^{\prime}$ and $c^{\prime}$ are bisecants. Consequently $D_{1}^{\prime}$ and $D_{2}$ are conjugated in a cubic correspondence.

Since $l$ has two points in common with $\left(s^{\prime}\right)^{2}, \lambda^{3}$ rests on $\sigma^{3}$ in two points. The rays of space are in this way transformed into the
fourfold infinity of twisted cubics, which intersect each of the lines $a^{\prime}, b^{\prime}, c^{\prime}$ and the curve $\sigma^{2}$ twice.

A plane $\Phi$ is transformed into a cubic surface passing through $a^{\prime}, b^{\prime}, c^{\prime}$ and $\sigma^{3}$. The images of two planes have these four lines and the image $\lambda^{3}$ of their line of intersection in common.
5. A tangent plane of the limiting surface $\boldsymbol{G}$ is the image of the circles which pass through a given point. The involution ( $\delta_{1}, \delta_{2}$ ) therefore (by \$4) has the following property: A system of coaxial circles is transformed into a class of circles with inclex three.

This class contains six circles with radius zero and three straight lines. The singular circles form three coaxial systems (\$1) and a class with index three ( $\$ 3$ ).

To each singular circle a system of coaxial circles is conjugated; these systems form four classes.

The image of a system of coaxial circles contains eight singular circles.
6. Evidently the representation of the field of circles on the points of space enables us to deduce from each involution in the latter an involution in the field of circles and vice versa.

A particularly simple involution is obtained as follows. On every ray $h$ which meets $O Z$ at right angles the paraboloid $\mathbf{G}$ determines an involution of conjugated pairs ( $P, P^{\prime}$ ). In the field of circles the analogon hereof is the corŕespondence which conjugates to each other two circles intersecting orthogonally and having the same power with respect to a fixed point $O$.

The point $P^{\prime}$, conjugated to $P$, is the intersection of the ray $h$ with the polar plane $\pi$ of $P$. If $P$ lies on $O Z$, then for $h$ may be taken any perpendicular to $O Z$ passing through $P$. Since $\pi$ now is perpendicular to $O Z$, to $P$ will be conjugated every point of the line of infinity of $z=0$.

A point of $\mathbf{G}$ lies in its own polar plane and therefore constrtutes a coincidence of the correspondence. When $P$ reaches the rertex of $G$ or the point at infinity of $O Z$, then $P^{\prime}$ is an arbitrary point of $z=0$ or of $z=\infty$.

If $P$ moves along a line $l$, then $h$ describes a ruled quadric $\rho^{2}$ and $\pi$ a pencil of planes projective with $\varrho^{2}$, so the locus of $P^{\prime}$ is a twisted cubic $\lambda^{3}$. The polar line $l^{\prime}$ of $l$ meets $\varrho^{2}$ in two points $P^{\prime}$; each plane through $l^{\prime}$ contains besides these two points still another point $P^{\prime}$ not lying on $l^{\prime}$. Hence $l^{\prime}$ is a chord of $\lambda^{\prime}$. So is $l$, for its points of intersection with $G$ are roincidences.
7. To the points $P^{\circ}$ of a plane $\Psi$ correspond the points $P^{\prime}$ of a cubic surface $\Psi^{3}$. Two such surfaces in the first place have the
curve $\lambda^{8}$ in common, which is the image of the line of intersection of the two corresponding planes. In order to obtain a proper insight into the meaning of the figure which they have in common in addition to this, we observe that the involution ( $P, P^{\prime}$ ) is a particular case of the following correspondence.

Let a quadric surface $\boldsymbol{T}^{2}$ be given and the pair of polar lines $d, l^{\prime}$. Tbrough a point $P$ the straight line $t$ is drawn which meets $d$ and $d^{\prime}$; the polar plane $\pi$ of $P$ defines on $t$ the point $P^{\prime}$, which we conjugate to $P$.

The points of intersection of $d$ and $\boldsymbol{\Phi}^{2}$ we denote by $E_{1}, E_{2}$, those of $d^{\prime}$ and $\boldsymbol{\Phi}^{2}$ by $E_{1}^{\prime}, E^{\prime}$. The straight line $E_{1} E_{1}^{\prime}$ lies in $\boldsymbol{\Phi}^{3}$; to each of its points $P$ evidently is conjugated any of its points. To each point of $d$ corresponds every point of $d$ '. Thus all the edges of the tetrahedron $E_{1} E_{2} E_{1}^{\prime} E_{\text {, }}^{\prime}$ are singular', so that these six lines are conjugated to their points of transit through a plane $\Psi$. In addition to the curve $\lambda^{3}$ two surfaces $\Psi^{3}$ then have these six singular lines in common.

If $\boldsymbol{\Phi}^{2}$ now again is replaced by $\mathbf{G}$, then $d$ becomes the axis $O Z$, $d^{\prime}$ is the line at infinity of $z=0$ and the other four singular lines are to be found in the imaginary lines along which $\mathbf{G}$ is intersected by $z=0$ and $z=\infty$.
8. If $P$ is caused to move along a line $l$, which meets $O Z$, then $h$ describes a system of parallel lines which is projective to the pencil constituted by the polar line of $P$ with respect to the parabola in the plane throngh $l$ and $O Z$. The points $P^{\prime}$ now are situated on a rectangular hyperbola which by the line at infinity of $z=0$ is completed to a $\lambda^{3}$.

By the correspondence of the orthogonal circles, which is alluded to in $\$ 6$ a system of coaxial circles is again transformed into a class with inderc three. The circles with radius zero are coincidences. The two circles of a pair are real only if they have a negative power with respect to $O$. When $O$ lies without a circle, then the conjugated circle has an imaginary radius.


[^0]:    ${ }^{1}$ ) These Proceedings XIX, p. 1130.

