## Huygens Institute - Royal Netherlands Academy of Arts and Sciences (KNAW)

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J.A. Schouten, On the number of degrees of freedom of the geodetically moving system and the enclosing euclidian space with the least possible number of dimensions, in: KNAW, Proceedings, 21 I, 1919, Amsterdam, 1919, pp. 607-613

Mathematics. - "On the number of degrees of freedom of the yeodetically moving system and the enclosing euclidian space with the least possible number of dimensions". By Prof. J. A. Schouten. (Communicated by Prof. J. Cardinaal).
(Communicated in the meeting of May 25, 1918).
Suppose $k$ to be a non-special curve in a finite part $X_{n}$ of a general space of $n$ dimenșions, containing no singular points and where only one geodetic line exists between two arbitrary points. Assuming in a point () on $k$ a system of $n$ mutually independent directions, we can move this system geodetically along $k$.

This geodetic moving can be geometrically defined in the following way. $X_{n}$ can always be placed in a euclidian space of $\frac{n(n+1)}{2}$ dimensions, without changing its linear element. There exists in this space a space $Y_{n}$ developable on a euclidian space of $n$ dimensions, tangent to $X_{n}$ in $k$. The geodetically moving directions will now ${ }^{-}$ coincide at any moment with the directions moving parallel to themselves in the euclidian space $Y_{n}$. It appears analytically that. the known covariant differential of a directed quantity e.q. a vector is a common differential judged from a geodetically moving system of directions. Hence if $\mathbf{v}$ is a vector stationary with respect to this system, $\mathbf{v}$ satisfies the differential-equation:

$$
d \mathbf{v}=0
$$

or in co-ordinates:

$$
d v^{\prime}+\left\{\begin{array}{c}
\mu v \\
\lambda
\end{array}\right\} v^{\mu} d x^{\nu}=0,
$$

and this equation then gives the analytical definition of the notion geodetic moving. ${ }^{\text {i }}$ ) A geodetic line is claracterised by the property that its linear element forms at every point the same angles with a system moving geodetically along the line.

[^0]Starting from a point $O$ a system of directions is now geodetically ' moved along a closed curve. On returning to $O$ the system will generally appear to have rotated. Dependent on the choice of the curve it is generally possible to obtain in this manner $\infty{ }^{\frac{n(n-1)}{2}}$ positions of the system. If this number is for one point and hence for every point of the area $o^{N}$, we call $N$ the number of degrees of freedom of the gendetically moving system. Now the following theorem exists:

1. The number of dimensions of the euclidian space, in which a given space $X_{n}$ may be placed, without changing its linear element, is at most equal to the number of degrees of freedom belonging to the geodetically moving system increased- with $n$.

We will prove this theorem. If the number of degrees of freedom is smaller than $\frac{n(n-1)}{2}$, there will remain invariant $r$ mutually perfectly perpendicular directions of $p_{1}, p_{3}, p_{3}, \ldots$ dimensions $p_{1}+\ldots+p_{r}=n$ (by direction of two dimensions or 2-direction we mean a plane direction, etc.). The number of possibilities exactly corresponds to the number of manners, in which $n$ can be written as the sum of whole positive numbers. We imagine the $r$ invariant directions marked once for all in $O$. The system then may be brought in every point of $X_{n}$, always by geodetically moving. The invariant $p_{j}$-direction, $j=1 \ldots, r$, will then define at every point a $p_{j}$-direction, and it is the question whether these directions will compose a system of $\infty^{n-p_{j}}$ carved spaces $P_{j}$ of $p_{j}$ dimensions. This is a Pfaftian problem in a general space:

We select a definite invariant direction, say the $p_{3}$-direction, and for convenience, salke we shall write $p$ for $p_{0}$. If wenow define the $p$-direction belonging to this direction at every point by the simple $p$-vectors, ${ }_{p} \mathbf{v}=\mathbf{v}_{1} \cap \mathbf{v}_{p}$, which all pass into one another by geodetically moving and likewise the perfectly perpendicular ( $n$ — $p$ )-drrection to this, by ${ }_{q} \mathbf{w}=\mathbf{w}_{1} \ldots \mathbf{w}_{q}, q=n-p$, then:

$$
d_{p} \mathbf{v}=0, \quad d_{q} \mathrm{~W}=0,
$$

hence:

$$
\nabla_{q^{\prime}} \mathrm{v}=0, \quad \nabla_{q} \mathrm{~W}=0 .
$$

It is worth mentioning, that the vectors $\mathrm{v}_{k}, k=1, \ldots, p$, do not pass into each other by geodetically moving and hence $d \mathbf{v}_{k}=\equiv=0$. The same holds good for $\mathbf{w}_{l}, l=1, \ldots, q$. If now the linear element
be $d \mathbf{x}$, the usual formulation of a problem as ander consideration, is as follows. ${ }^{1}$ )

Given the $p n$ functions of $x^{1}, \ldots, x^{n}$ :
$v_{k}{ }^{1}, \ldots, v_{k}{ }^{n} \quad ; \quad k=1, \ldots, p$
(the contravariant characteristic numbers of the vectors $\mathbf{v}$ ), and the $q n$ functions:

$$
w_{l_{1}}, \ldots, w w_{l n} \quad ; \quad l=1, \ldots, q
$$

(the covariant chararteristic numbers of the vectors w), satisfying the relation :

$$
\stackrel{1, \ldots n}{\vdots} v_{k^{\prime}} w_{l}=0
$$

equivalent to

$$
\mathrm{v}_{k} \cdot \mathrm{w}_{l}=0
$$

we ask, when the system of the total differential-equations

$$
\left\|\begin{array}{cccc}
d x^{1} & \ldots & d x^{n} \\
v_{1}{ }^{1} & \ldots & v_{1}{ }^{n} \\
\vdots & \cdots & v_{1} \\
v_{p^{1}}{ }^{1} & \ldots & v_{p}{ }^{n}
\end{array}\right\|=0
$$

equivalent to

$$
d \mathbf{x} \quad \mathbf{v}_{1} \ldots \quad \mathbf{v}_{p}=0
$$

is perfectly integrable.
If $\mathbf{r}$ and $\mathbf{s}$ are two vectors, lying in the $p$-vector ${ }_{\mu} \mathbf{v}$, and consequently satisfying the relations:

$$
\mathbf{w} l \cdot \mathbf{r}=0 \quad, \quad \mathbf{w} l \cdot \mathbf{s}=0, \quad l=1, \ldots, q
$$

which is equivalent to:

$$
{ }^{1, \ldots,{ }^{n}}{ }_{w_{l a}, r^{2}}=0 \quad, \sum_{\wedge}^{1,}{ }^{\prime \prime n} w_{l, s^{2}}=0 \quad, \quad l=1, \ldots, q
$$

but being otherwise arbitrary, the conditions of integrability are, as known:

$$
{ }_{\mu, \nu}^{1,} \sum_{, n}^{\prime \prime}\left(\frac{\partial w_{l \mu}}{\partial x^{\prime}}-\frac{\partial w_{l \rho}}{\partial x^{\mu}}\right) r^{\mu} \boldsymbol{g}^{\nu}=0 ; \quad l=1, \ldots .
$$

These equations are generally covariant ${ }^{\prime}$ ) and are equivalent to:

$$
\mathbf{r} \mathbf{s}^{2} \nabla-\mathbf{w} l=0 ; \quad l=1, \quad \ldots, q
$$

${ }^{1}$ ) Cf. e.g. E. von Weber, Vorlesungen über das Prafy'sche Problem, pages 93 and f.f. 2) Owing to the circuinstance that the expression $\frac{\partial w_{l \mu}}{\partial x^{\nu}}-\frac{\partial w_{l \nu}}{\partial x^{\mu}}$ is generally covariant.

Now it follows from this mode of notation that they may be replaced by the invariant equation:

$$
\mathrm{r} \frown \mathrm{~s}^{2} \cdot \nabla \frown\left(\mathrm{w}_{1} \ldots \ldots \mathrm{w}_{\mathrm{q}}\right)=\mathrm{r} \frown \mathrm{~s}^{2} \cdot \nabla \frown \mathrm{q}^{\mathrm{w}}=0,
$$

or, as follows from the preceding, still more simplinied without making use of two auxiliary rectors:

$$
\left.p \mathbf{V}^{2} \cdot \nabla \frown{ }_{q} \mathbf{W}=0 .^{1}\right)
$$

But this equation is idenlically true, $\nabla \frown_{q} \mathbf{w}$ being a multiplesum of isomers of $\nabla_{斤} \mathbf{W}$, and $\nabla_{\boldsymbol{f}} \mathbf{W}$ being zero.

As the plane tangent-spaces of $p_{3}$ dimensions, in the various points of the spaces $P_{j}$ have $p_{3}$-directions, which by means of geodetic motion pass into each other and in the invariant $p_{\jmath}$-direction in $O$, but never in any other direction, two spaces $P_{j}$ can therefore never intersect. A geodetic line in $X_{n}$, which has a linear elemont in common with a definite space $P_{3}$, is apparently altogether contained in that space and in that spare it is geodetic too. Hence two different spaces $P_{j}$ can never be tangent to one another. Therefore we call the spaces $P_{j}$ parallel ones. As any geodetic line having two points in common with a $P_{j}$ space, falls completely within that space, which will be proved later on, we call a $P_{j}$ space geodetic. The $r$ obtained systems of parallel geodetic spaces $P_{1}, \ldots, P_{1}$ are at every point of $X_{n}$ perfectly perpendicular to each other.

We shall first contemplate the case $r=2, p_{1}=p, p_{2}=q$. The parameter-spaces of $n-1$ dimensions of the primitive variables $n^{1}, \ldots, x_{p}$ are placed thas that each of them contains $\infty^{n-\mu-1}$ spaces $P$, those of $a^{p+1}, \ldots, x^{n}$ likewise with regard to the spaces $Q$. At every point we place the mutually perfectly perpendicular $p$-resp. $q$-vectors ${ }_{p} \mathbf{v}$ and ${ }_{q} \mathbf{w}$. The measure-vectors $\mathbf{e}^{\prime}, x=1, \ldots, p$ are then situated in ${ }_{\mu} \mathrm{V}$ and for the measure-vectors $\mathrm{e}^{\prime}{ }_{\mu}, \mu=p+1, \ldots, n$ the same holds good with regard to ${ }_{q} \mathbf{w}$. Because $\boldsymbol{e}^{\prime}, \perp \boldsymbol{\theta}^{\prime}{ }_{\mu}$ we have

$$
g_{\nsim \nu}=\mathrm{e}_{\gamma}^{\prime} \cdot \mathbf{e}_{\mu}^{\prime}=0 ; \quad \begin{aligned}
& x=1, \ldots, p \\
& \mu=p+1, \ldots, n
\end{aligned}
$$

hence the quadratic form $d s^{2}$ may be written thus:

Now may be demonstrated, that $g_{v}$ is independent of $x^{\mu+1}, \ldots, x^{n}$, and likewise $g_{p}$, is independent of $x^{1}, \ldots, x^{p}$. It is always possible to choose a scalar $k$ as function of $x^{1}, \ldots, x^{n}$, so that:

[^1]$$
{ }_{q}{ }^{\mathbf{W}} \cdot\left(\nabla^{1} \cdot \mu \mathrm{v}\right)=0 .
$$
$$
{ }_{p} \mathbf{v}=\mathrm{ke}_{1}^{\prime} \cdot \ldots \cdot \mathrm{e}_{p}
$$

Consequently :

By complete transvection with:

$$
\mathbf{e}_{\mu} \ldots \mathbf{e}_{x+1} \mathbf{e}_{\mu}^{\prime} \mathbf{e}_{x-1} \ldots \mathbf{e}_{1} \mathbf{e}^{\prime}
$$

all the terms except the $(x+1)$-th give zero, hence:

$$
\left(\begin{array}{ll}
\left.\frac{\partial}{\partial x^{\prime}} a_{\mu}\right) a_{\mu}=0 & x=1, \ldots, p \\
& \mu, v=p+1, \ldots, n .
\end{array}\right.
$$

Now :

$$
\bar{g}_{\mu \nu}=a_{\mu} a_{\nu}
$$

and

$$
\left(\frac{\partial}{\partial x_{\mu}} a_{j}\right) a_{\mu}=a_{\mu \nu} a_{y}=\left[\begin{array}{c}
x v \\
\mu
\end{array}\right]=a_{i \mu} a_{\mu}
$$

thus

$$
\frac{\partial g_{\mu \nu}}{\partial a^{\alpha}}=a_{\mu,} a_{\mu}+a_{\mu} a_{\nu \lambda}=0 .
$$

* Hence the linear element in the $Q$ spaces is independent of $x^{2}, \ldots, x^{\prime}$; the corresponding' property of the $P$ spaces relative to $x^{p+1}, \ldots \ldots v^{n}$ is similarly demonstrated.

This property, can also be expressed in the following manner.
-1I.' If in 'a general space $X_{n}$ is placed a system of $\infty^{n-p}$ parallel geodetical spaces of $p$ dimensions $P$, having perfectly perpendicular. to it a system of $\infty p$ similar spaces $Q$ of $n-p$ dimensions, a figure in'a definite $P$-space will be congruently projected by the $Q$-spaces on all the other $P$-spaces.

For: $p=1$ this is the well-known property that the distance of two definite $Q$-spaces measured along the $P$-lines is constant. So we can here introduce in this case for primitive variable $x^{1}$ the curve length measured along these lines from a definite space, the spaces remaining parameter-spaces. Hence the linear element may then be expressed in the following way:

$$
d s^{2}=d x^{2}+\dot{\Sigma}_{\mu, \nu}^{2, n} g_{\mu \nu} d x^{\mu} d x^{\nu}
$$

in which the $g_{\mu \nu}$ do not depend on $x^{1} \cdot{ }^{1}$ ).
As, however, a quadratic differential form in $n-1$ variables can

[^2]Proceedings Royal Acad. Amsterdam. Vol. XXI.
always be written as a sum of $\frac{n(n-1)}{2}$ quadrates of complete differentials, $d s^{2}$ can be reduced to a sum of $\frac{n(n-1)}{2}+1$ similar quadrates. Hence the space $X_{n}$ can be placed in this case in a euclidian space of

$$
\frac{n(n-1)}{2}+1=\frac{(n-1)(n-2)}{2}+n
$$

dimensions. As the number of degrees of freedom of the geodetic moving system amounts exactly to

$$
\frac{(n-1)(n-2)}{2}
$$

the required proof has been furnished.
If we now return to the case $r=2, p_{1}=p, q_{2}=q$, the number of degrees of freedom is $\frac{p(p-1)}{2}+\frac{q(q-1)}{2}$. The quadratic form breaks up into two forms, which may be written as a sum of $\frac{q(q+1)}{2}$ resp. $\frac{p(p+1)}{2}$ quadrates. Therefore the space $X_{n}$ can be placed within a euclidian space of

$$
\frac{p(p+1)}{2}+\frac{q(q-1)}{2}=\frac{p(p-1)}{2}+\frac{q(q-1)}{2}+n
$$

dimensions, and here again the required proof has been furnished.
The case $q>2$ may be reduced to the preceding one. For this purpose the differential form is divided into two. The spaces of one of the systems, say $P_{2}$, then again contain themselves at least two perfectly perpendicular systems of parallel geodetic spaces. Then the second part of the differential form is once more divided etc.

If owing to the existence of the $P_{j}$-system the division of the differential form is:

$$
d s^{\mathbf{2}}=\mathbf{a}^{2} \stackrel{2}{\cdot} d \mathbf{x}^{2}=\mathbf{a}_{p}^{2} \stackrel{2}{2} \cdot d \mathbf{x}^{\mathbf{2}}+\mathbf{a}_{q}{ }^{\mathbf{2}} \cdot d_{\mathbf{x}}^{\mathbf{2}}
$$

in which $a_{p}$ and $a_{q}$ are the ideal radices of the two parts of the fundamentaltensor $a^{2}$, the differential equation of a geodetic line will be:

$$
d \frac{d \mathbf{x}}{d s}=d\left(\mathbf{a} \cdot \frac{d \mathbf{x}}{d s}\right) \mathbf{a}=d\left(\mathbf{a}_{p} \cdot \frac{d \mathbf{x}}{d s}\right) \mathbf{a}_{p}+d\left(\mathbf{a}_{q} \cdot \frac{d \mathbf{x}}{d_{s}}\right) \mathbf{a}_{q}=\mathbf{0}
$$

$a_{p}$ compossing itself only of the measure vectors $e_{1}^{\prime}, \ldots, e_{p}^{\prime}$ and $\mathbf{a}_{q}$ only of $\dot{\mathbf{e}}_{p+1}, \ldots, \dot{\mathbf{e}}_{n}$, we have :

$$
d\left(\mathbf{a}_{p} \cdot \frac{d \mathbf{x}}{d s}\right) \mathbf{a}_{p}=0 \quad, \quad d\left(\mathbf{a}_{q} \cdot \frac{d \mathbf{x}}{d s}\right) \mathbf{a}_{q}^{\prime}=0
$$

from which the property is inferred:
III. In the proposition made in formulating 11 the projection of a geodetic line by means of $Q$ spaces on a $P$ space, or vice versa, is, as far as existent, a geodetic one itself.

If two points $A$ and $B$ are situated in a $P$ space $P_{1}$, the projections of these points on all spaces comeide. Hence the projections on a $Q$ space of the line $A B$ geodetic in $X_{n}$ passes twice. through the same point, being at the same time geodetic in $Q$, which is only possible when that projection has degenerated into a point. But then the geodetic line $A B$ mast be situated altogether in a $P$ space, e.g. in the present case in $P_{1}$.

Hence any geodetic line, having two points in common with a $P$-space, is entrely contained in that space.


[^0]:    $\left.{ }^{1}\right)$ The covariant notations in this paper are the customary ones, but the contravariant characteristic numbers of the linear element $d \mathbf{x}$ are written contravariant agreeing to G. Hessenberg, but contrary to G. Rigci and T. Levi Givita. For the invariant notations, the here used direct analysis, cf. "Ueber die direkte Analysis der neueren Relativitätstheorie", a paper presented to the "Koninkl. Akademie v. W.' together with this note. (Verh. Vol. $12 \mathrm{~N}^{\prime \prime} .6$ ).

[^1]:    ${ }^{1}$ ) This equation can also be obtained very easily by means of the direct analysis used here. Another form of the same equation is:

[^2]:    in 1), This formula has already been derived by T. Levi Givita. Nozione di parallelismo in una varietà qualunque e consequente specificazione geometrica della curvatura Riemanniana. Rend. di Pal. 42 (17).

