Hydrodynamics. - A remark on a formula for the resistance experienced by a body in a fluid, given by Oseen and Zeilon. By J. M. Burgers. (Mededeeling $\mathrm{N}^{0} .15$ uit het Laboratorium voor Aero- en Hydrodynamica der Technische Hoogeschool te Delft). (Communicated by Prof. P. Ehrenfest).
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§ 1. One of the most interesting results which can be deduced from Oseen's hydrodynamical theory is the relation between the resistance $W$ experienced by a body in a current of fluid of velocity $V$, and the inflow $Q$ in the wake behind it:

$$
\begin{equation*}
W=\varrho V Q \tag{1}
\end{equation*}
$$

( $\varrho$ being the density of the fluid). ${ }^{1}$ ) This relation is a consequence of the circumstance that the solution of Oseen's equations :

$$
\left.\begin{array}{c}
\varrho\left(v \triangle u_{i}-V \frac{\partial u_{i}}{\partial x_{1}}\right)=\frac{\partial q}{\partial x_{i}}-Y_{i}  \tag{2}\\
\sum_{j} \frac{\partial u_{j}}{\partial x_{j}}=0
\end{array}\right\}
$$

can be separated into two parts as follows : ${ }^{2}$ )

$$
\begin{equation*}
u_{i}=v_{i}+\frac{\partial \varphi}{\partial x_{i}} \tag{3}
\end{equation*}
$$

Here $\varphi$ is a potential (which, however, is not a solution of Laplace's equation), whereas the $v_{l}$ represent a motion with vorticity. The $v_{i}$ exist only in the wake behind the body, and are determined by the formulae:

$$
\begin{equation*}
\boldsymbol{v}_{i}=\frac{1}{4 \pi \varrho v} \iiint d \xi_{1} d \xi_{2} d \xi_{3} \frac{e^{-s}}{r} Y_{i} . \tag{4}
\end{equation*}
$$

[^0]In this expression $\nu$ represents the kinematical viscosity; further:

$$
s=k\left(r-x_{1}+\xi_{1}\right), \quad \text { where } \quad k=V / 2 v, \quad r=\sqrt{\sum\left(x_{j}-\xi_{j}\right)^{2}}
$$

the $Y_{i}$ are to be considered as functions of the $\xi_{i}$.
When we suppose that the $Y_{i}$ are zero everywhere outside of a region of limited extension, then we have for values of $x_{1}$, lying sufficiently far downstream of this region:

$$
\begin{equation*}
\iint d x_{2} d x_{3} v_{i}=\frac{1}{\varrho V} \iiint d \xi_{1} d \xi_{2} d \xi_{3} Y_{i} \tag{5}
\end{equation*}
$$

When we consider the case $i=1$, then the integral on the left hand side of this equation represents the inflow in the wake, taken with the opposite sign.

Now in eq. (2) the $Y_{i}$ represent the sum of the real or exterior forces $X_{i}$, acting on the fluid, and the "apparent" or "interior" forces $y_{i}$, which express the influence of the quadratic terms of the equations of hydrodynamics:

$$
\begin{equation*}
Y_{i}=X_{i}+y_{i}=X_{i}-\varrho \sum_{j} u_{j}\left(\frac{\partial u_{i}}{\partial x_{j}}-\frac{\partial u_{j}}{\partial x_{i}}\right) \tag{6}
\end{equation*}
$$

As we may write:

$$
\begin{equation*}
y_{i}=-\varrho \sum_{j} \frac{\partial}{\partial x_{j}}\left(u_{j} u_{i}\right)+\frac{1}{2} \varrho \frac{\partial}{\partial x_{i}}\left(\sum_{j} u_{j}^{2}\right) \tag{a}
\end{equation*}
$$

we have:

$$
\begin{equation*}
\iiint d \xi_{1} d \xi_{2} d \xi_{3} y_{i}=0 \tag{7}
\end{equation*}
$$

(supposing that the quantities $y_{i}$ tend to zero sufficiently fastly, when we go away to great distances), and so:

$$
\begin{equation*}
\iiint Y_{i} d \xi_{1} d \xi_{2} d \xi_{3}=\iiint X_{i} d \xi_{1} d \xi_{2} d \xi_{3}=F_{i} \tag{8}
\end{equation*}
$$

where the $F_{i}$ represent the components of the resultant of the exterior forces.

All these remarks refer to the case of a field of unlimited extension. In order to apply them to the case of the motion along a body, we shall imagine the body to be taken out of the field, and to be replaced by fluid at rest. At the same time we introduce a system of forces, acting in the points that were formerly occupied by the surface of the body, and chosen in such a way, that they exactly represent the influence which the body exerted on the fluid. When the motion of the fluid in the neighbourhood of the body is given, such a system of forces can be determined by means of equations (2) from the discontinuities, which the motion of the fluid shows at this surface. We shall not inquire into the nature of this system of forces, as all that we want is that the resultant of these forces is equal and opposite to the resistance expe-
rienced by the body. Then formula (5), combined with (8), at once leads to formula (1).
§ 2. Now Oseen and Zeilon have given a formula for the resistance which applies to the case of very small viscosity (very high Reynolds' numbers), and which shows a different form : ${ }^{1}$ )

$$
\begin{equation*}
W=\frac{1}{2} \varrho \iint d x_{2} d x_{3} v^{2} \tag{9}
\end{equation*}
$$

Here $v$ represents the value of $v_{1}$ in the cylindrical part of the wake which extends immediately behind the body; it is a function of $x_{2}$ and $x_{3}$ only. The formula is demonstrated for the case of two-dimensional motion, but the demonstration can be extended to the case of a body having rotational symmetry about the $x_{1}$-axis. As the inflow in the wake is given by:

$$
\begin{equation*}
Q=-\iint d x_{2} d x_{3} v \tag{10}
\end{equation*}
$$

formula (1) seems to be not applicable to this case.
The object of the present note is to show that the origin of this discrepancy is to be found in the circumstance, that formula (9) is derived from an integration of the pressure $p$ over the surface of the body, and that in the calculation of $p$ from the quantity $q$, which occurs in equations (2), terms of the second degree in the $u_{i}$ have been taken into account. In fact leaving aside the hydrostatical part of the pressure, we have:

$$
\begin{equation*}
p=q-\frac{1}{2} \varrho \Sigma u_{j}^{2} \tag{11}
\end{equation*}
$$

The determination of the field of flow on the other hand is based wholly upon the application of the reduced equations, from which all quadratic terms have been omitted.

In order to study this point more closely we may investigate by which system of forces the motion, calculated by ZEILON, could be held up when the body was absent and was replaced by fluid at rest.

We shall restrict ourselves to the case of two-dimensional motion. Then the solution of equations (2) may be written as follows: ${ }^{2}$ )

$$
\left.\begin{array}{l}
\left.\mathbf{u}_{1}=\frac{1}{2 \pi \varrho V} \iint d \xi_{1} d \xi_{2}\left[Y_{1}\left\{\frac{V}{v} \varepsilon-\frac{\partial}{\partial x_{1}}(\lg \tau+\varepsilon)\right\}-Y_{2} \frac{\partial}{\partial x_{2}}(\lg \tau+\varepsilon)\right]\right) \\
\mathbf{u}_{2}=\frac{1}{2 \pi \varrho V} \iint d \xi_{1} d \xi_{2}\left[-Y_{1} \frac{\partial}{\partial x_{2}}(\lg \tau+\varepsilon)+Y_{2} \frac{\partial}{\partial x_{1}}(\lg \tau+\varepsilon)\right] \tag{12}
\end{array}\right\}
$$

[^1]where:
$$
r=V \overline{\left(x_{1}-\xi_{1}\right)^{2}+\left(x_{2}-\xi_{2}\right)^{2}} \quad, \quad \varepsilon=e^{k\left(x_{1}-\xi_{1}\right)} K_{0}(k r), \quad k=V / 2 v
$$

When the value of Reynolds' number $R=V D / v$ ( $D$ being the diameter of the body) is sufficiently high, we may replace these formulae by the following approximations: ${ }^{1}$ )

$$
\begin{equation*}
u_{1}=\frac{\partial \varphi}{\partial x_{1}}+v, \quad u_{2}=\frac{\partial \varphi}{\partial x_{2}} \tag{13}
\end{equation*}
$$

where the potential $\varphi$ is determined by:

$$
\begin{equation*}
\varphi=\frac{1}{2 \pi \varrho V} \iint d \xi_{1} d \xi_{2}\left[-Y_{1} \lg r+Y_{2} \operatorname{arctg} \frac{x_{2}-\xi_{2}}{x_{1}-\xi_{1}}\right] \tag{14}
\end{equation*}
$$

while $v$ has the value:

$$
\begin{equation*}
v=\frac{1}{\varrho V} \int_{-\infty}^{x_{1}} d \xi_{1} Y_{1} \tag{15}
\end{equation*}
$$

These expressions can be used in all parts of the field, except at distances downsiream of the region where the forces $Y_{i}$ are supposed to act, of about the order $10^{-5} R D$ and greater, as at such distances the diffusion of the vorticity in consequence of the viscosity may no longer be neglected. We shall come back to this point afterwards; presently we shall consider only those parts of the field that are not lying at such distances downstream.

Then we may say that, as far as the potential $\varphi$ is concerned, every force $Y_{1}$ may be considered as the seat of a (negative) source of strength $-Y_{1} / \varrho V$, and every force $Y_{2}$ as the seat of a vortex of strength $+Y_{2} / \varrho V$. Formula (15) moreover shows that downstream from the region where the forces are applied, $v$ is independent of $x_{1}$; upstream of this region it is zero.
§3. Now the solution obtained by Oseen for the motion along a

[^2]body in the case of high Reynolds' numbers has just the same form (13), were $\varphi$ and $v$ are determined by the conditions: ${ }^{1}$ )
\[

$$
\begin{align*}
& \Delta \varphi=0 \quad \text { in the whole field }  \tag{a}\\
& \text { at the front surface }  \tag{b}\\
& \text { of the body } \\
& \left.\begin{array}{rl}
V+\frac{\partial \varphi}{\partial x_{1}}+v & =0 \\
\frac{\partial \varphi}{\partial x_{2}} & =0
\end{array}\right\} \text { at the back of the body } . \ldots .\{  \tag{c}\\
& \varphi=0 \quad \text { at infinity } \tag{e}
\end{align*}
$$
\]

In order to determine the magnitude of the forces $Y_{i}$ necessary to produce this motion, we shall consider the field of flow determined by the potential $\varphi$ only, and completed in the interior of the body by a motion with the velocity $-V$ parallel to the $x_{1}$-axis. (It has to be kept in mind, that in our equations the quantities $u_{i}$ represent the motion that has to be superposed on the general velocity $V$ of the fluid in the positive direction of the $x_{1}$-axis; when we leave out this velocity everywhere, we get the velocity $-V$ in the interior of the space occupied by the body).

It is to be seen from $\left(16^{b}\right),\left(16^{c}\right),\left(16^{d}\right)$ that along the front surface of the body the field so determined presents a discontinuity of the tangential component of the velocity, but not of the normal component, whereas along the back surface both components are discontinuous. We thus may regard this surface as the seat of a system of vortices and of sources. Calling $\beta$ the strength of the sources per unit length, $\gamma$ the vorticity per unit length, and denoting an element of the circumference by $d s$ (measured in the counterclockwise direction), we have the following relations:

$$
\begin{align*}
& \text { along the front surface: } \quad \beta=\frac{\partial \varphi}{\partial n}+V \cos \left(n x_{1}\right)=0  \tag{a}\\
&  \tag{b}\\
& \qquad=\frac{\partial \varphi}{\partial s}-V \sin \left(n x_{1}\right) \quad . \tag{c}
\end{align*} \quad .
$$

In consequence of what has been said in § 2 we see that the motion in the absence of the body could be obtained by applying a system of forces, acting in the points of the surface and determined by the equations:

$$
\begin{equation*}
Y_{1}=-\beta \varrho V, \quad Y_{2}=+\gamma \varrho V \tag{18}
\end{equation*}
$$

where the intensities $Y_{1}, Y_{2}$ are referred to unit length.

[^3]The resultant of this system of forces, taken along the axis of $x_{1}$, has the value:

$$
\begin{equation*}
-W=\int d s Y_{1}=\varrho V \int d s v \cos \left(n x_{1}\right)=-\varrho V Q \tag{19}
\end{equation*}
$$

in accordance with formula (1).
§ 4. Thus far we have limited ourselves to the linear equations. Now we shall pass over to a consideration of the terms of the second degree. In order to obtain these terms we have to introduce the "interior" forces $y_{i}$, the components of which in our case are given by the expressions:

$$
\begin{equation*}
y_{1}=+\varrho u_{2} w, \quad y_{2}=-\varrho u_{1} w \tag{20}
\end{equation*}
$$

where $w$ denotes the vorticity, present in the real motion (that is, in the motion which is obtained, when to the field described in § 3 , is added the velocity $v$ in the wake).

Vortex motion is present (a) at the surface of the body, (b) in the wake.
We begin with the "interior" forces arising from the vortex layer at the surface of the body. At the front side the intensity of this layer is determined by the quantity $\gamma$, given in eq. $\left(1^{b}\right)$; at the back side the intensity is zero, as in the motion that results from the combination of the field determined by $\varphi$ with the velocity $v$, no discontinuities occur at the back side. So we have to consider the front side only. When we integrate the expressions (20) over the thickness of this layer, we get for the intensities of the forces per unit length :

$$
\begin{align*}
& \bar{y}_{1}=\frac{1}{2} \varrho \gamma\left\{\left(u_{2}\right)_{e}+\left(u_{2}\right)_{i}\right\}=\frac{1}{2} \varrho \gamma \frac{\partial \varphi}{\partial x_{2}} . . . . . .  \tag{a}\\
& \bar{y}_{2}=-\frac{1}{2} \varrho \gamma\left\{\left(u_{1}\right)_{e}+\left(u_{1}\right)_{i}\right\}=\frac{1}{2} \varrho \gamma\left(V-\frac{\partial \varphi}{\partial x_{1}}\right) . \tag{b}
\end{align*}
$$

(the indices $e, i$ respectively refer to the exterior and to the interior side of the surface of discontinuity).

The interior forces exert just the same influence on the field as the real or exterior forces do. Now as we have said, we may consider the $Y_{i}$ as representing the total forces; hence when we write:

$$
\begin{equation*}
Y_{1}=X_{1}+\bar{y}_{1}, \quad Y_{2}=X_{2}+\bar{y}_{2} \tag{22}
\end{equation*}
$$

the quantities $X_{1}, X_{2}$ will represent the components of the forces that have to be applied by exterior means.

We calculate the resultant of the forces $\bar{y}_{1}$. Making use of $\left(17^{b}\right)$ and $\left(16^{b}\right)$, we obtain:

$$
\int \bar{y}_{1} d s=\frac{1}{2} \varrho \int d s\left[\left(V+\frac{\partial \varphi}{\partial x_{1}}\right)^{2}+\left(\frac{\partial \varphi}{\partial x_{2}}\right)^{2}\right] \cos \left(n x_{1}\right) .
$$

This integral can be calculated as follows. ${ }^{1}$ ) Firstly we extend it along

[^4]the whole circumference of the body, which adds to it the amount: $\frac{1}{2} \varrho \int d x_{2} v^{2}$. When we write: $\Phi=V x_{1}+\varphi$, our integral takes the form:
$$
\frac{1}{2} \varrho \int d x_{2}\left[\left(\frac{\partial \Phi}{\partial x_{1}}\right)^{2}+\left(\frac{\partial \Phi}{\partial x_{2}}\right)^{2}\right]
$$
where the integration still has to be performed in the counterclockwise direction. To this integral we add the quantity:
$$
-\varrho \int\left[d x_{2}\left(\frac{\partial \Phi}{\partial x_{1}}\right)^{2}-d x_{1} \frac{\partial \Phi}{\partial x_{1}} \frac{\partial \Phi}{\partial x_{2}}\right]=-\varrho \int d x_{2} v^{2}
$$

Our integral now becomes:

$$
-\frac{1}{2} \varrho \int\left[d x_{2}\left\{\left(\frac{\partial \Phi}{\partial x_{1}}\right)^{2}-\left(\frac{\partial \Phi}{\partial x_{2}}\right)^{2}\right\}-2 d x_{1} \frac{\partial \Phi}{\partial x_{1}} \frac{\partial \Phi}{\partial x_{2}}\right]
$$

The latter expression represents the real part of the integral:

$$
\frac{1}{2} i \varrho \int d z\left(\frac{d \chi}{d z}\right)^{2}
$$

where $z=x_{1}+i x_{2}$ and $\chi$ denotes the complex potential related to $\Phi$. As at infinity we have the expansion:

$$
\chi=V z+\frac{\mathrm{Q}}{2 \pi} \lg z+\ldots
$$

the value of the complex integral becomes: - $\varrho V Q$. From this we easily obtain:

$$
\begin{equation*}
\int \frac{\overline{y_{1}}}{} d s=-\varrho V Q+\frac{1}{2} \varrho \int d x_{2} v^{2} \tag{23}
\end{equation*}
$$

Now we can calculate the resultant of the exterior forces $X_{1}$. Using (19) and (23) we obtain:

$$
\begin{equation*}
-W^{\prime}=\int d s X_{1}=-\frac{1}{2} \varrho \int d x_{2} v^{2} \quad . . . . \tag{24}
\end{equation*}
$$

This is Zeilon's result, quoted before (form. (9)).
It is not difficult to ascertain that the resultant of the forces $X_{1}$ and $X_{2}$ at every point stands perpendicular to the surface of the body, and represents the pressure, calculated from formula (11), supposing the additive constant that occurs in the expressions for $q$ and $p$ is chosen in such a way, that the pressure at infinity has the value $-\frac{1}{2} \varrho V^{2} .^{1}$ )
§5. We have seen how Zeilon's formula can be obtained by a

[^5]consideration of the "interior" (or second order) forces, acting in the points of the surface of the body.

However, forces of just the same kind arise from the vorticity that is present in the wake. These forces will have some influence on the whole field of motion. Especially the components $y_{1}$ may be considered as producing a system of (negative) sources, and hence the outflow $Q$ at great distances from the body will have to be diminished by the amount:

$$
\begin{equation*}
\iint d x_{1} d x_{2} \frac{y_{1}}{\varrho V}=\frac{1}{V} \iint d x_{1} d x_{2} u_{2} w \tag{25}
\end{equation*}
$$

where the integration extends over the wake.
From equations (12) we obtain the following expression for the vorticity:

$$
\begin{equation*}
w=\frac{1}{2 \pi \varrho v} \iint d \dot{\xi}_{1} d \xi_{2}\left[-Y_{1} \frac{\partial \varepsilon}{\partial x_{2}}+Y_{2} \frac{\partial \varepsilon}{\partial x_{1}}\right] \tag{26}
\end{equation*}
$$

At the same time the full expression for $u_{2}$ may be written as follows:

$$
\begin{equation*}
u_{2}=\frac{\partial \varphi}{\partial x_{2}}+\frac{v}{V} w \tag{27}
\end{equation*}
$$

A consideration of the orders of magnitude of the two terms, occurring in the expression for $\boldsymbol{w}$, shows us that the first term is preponderant, and that the second one may be neglected.

When we go away from the body in the direction of the positive axis of $x_{1}$, the derivative $\partial \varphi / \partial x_{2}$ decreases as $r^{-2}$. Hence for sufficiently great values of Reynolds' number the integral:

$$
\frac{1}{V} \iint d x_{1} d x_{2} \frac{\partial \varphi}{\partial x_{2}} w
$$

which represents the first part of (25), may be limited to that part of the wake, in which the diffusion of the vorticity is not yet appreciable. Then we may write:

$$
w=-\frac{d v}{d x_{2}}
$$

and so we get:

$$
-\frac{1}{V} \iint d x_{1} d x_{2} \frac{\partial \varphi}{\partial x_{2}} \frac{d v}{d x_{2}}=\frac{1}{V} \int d x_{2} v \frac{d}{d x_{2}}\left(\int d x_{1} \frac{\partial \varphi}{\partial x_{2}}\right)=\frac{1}{V} \int d x_{2} v \frac{\partial \varphi}{\partial x_{1}}
$$

where $\partial \varphi / \partial x_{1}$ has to be taken at the back of the body. Using (16c) we find for the latter expression:

$$
\begin{equation*}
-\frac{1}{V} \int d x_{2} v(V+v)=Q-\frac{1}{V} \int d x_{2} v^{2} \tag{28}
\end{equation*}
$$

§ 6. In order to calculate the second part of (25), that is $\frac{\nu}{V^{2}} \iint d x_{1} d x_{2} w^{2}$, we make use of the approximation:

$$
\varepsilon \cong\left(\frac{\pi}{2 k x_{1}}\right)^{1 / 2} e^{-\frac{k\left(x_{2}-\xi_{2}\right)^{2}}{2 x_{1}}}
$$

and write (compare (15) and the end of § 2):

$$
\int d \xi_{1} Y_{1}=\varrho V v\left(\xi_{2}\right)
$$

Then we obtain for the vorticity:

$$
\boldsymbol{w}=\frac{V}{2 \pi v} \int d \xi_{2} v\left(\xi_{2}\right) \frac{\pi^{1 / 2} k^{1 / 2}\left(x_{2}-\xi_{2}\right)}{2^{1 / 2} x_{1}^{3 / 2}} e^{-\frac{k\left(x_{2}-\xi_{v}\right)^{2}}{2 x_{1}}},
$$

or by means of a partial integration (writing $v^{\prime}\left(\xi_{2}\right)$ for $d v / d \xi_{2}$ ):

$$
\begin{equation*}
w=-\frac{V}{2 \pi v} \int d \xi_{2} v^{\prime}\left(\xi_{2}\right)\left(\frac{\pi}{2 k x_{1}}\right)^{1 / 2} e^{-\frac{k\left(x_{2}-\xi_{2}\right)^{2}}{2 x_{1}}} . \tag{29}
\end{equation*}
$$

Now we have to calculate:

$$
\frac{1}{4 \pi V} \int d \xi_{2} v^{\prime}\left(\xi_{2}\right) \int d \xi_{2}^{\prime} v^{\prime}\left(\xi^{\prime}{ }_{2}\right) \int d x_{1} \int d x_{2} \frac{1}{x_{1}} e^{-\frac{k}{2 x_{1}}\left[\left(x_{2}-\xi_{2}\right)^{2}+\left(x_{2}-\xi_{2}\right)^{2}\right]}
$$

The integration with respect to $x_{2}$ gives:

$$
\frac{1}{4 \pi V} \sqrt{\frac{\pi}{k}} \int d \xi_{2} v^{\prime}\left(\xi_{2}\right) \int d \xi_{2}^{\prime} v^{\prime}\left(\xi_{2}^{\prime}\right) \int d x_{1} \frac{1}{\sqrt{x_{1}}} e^{-\frac{k}{x_{1}}\left(\frac{\xi_{2}-\xi_{2}^{\prime}}{2}\right)^{\prime}}
$$

The integration with respect to $x_{1}$, considered separately, appears to be divergent when $x_{1}$ approaches $\infty$. The whole integral, however, is convergent on account of the circumstance that both:

$$
\int d \xi_{2} v^{\prime}\left(\xi_{2}\right)=0, \quad \text { and }: \quad \int d \xi_{2}^{\prime} v^{\prime}\left(\xi_{2}^{\prime}\right)=0
$$

Therefore we shall write our integral:

$$
\begin{equation*}
\lim _{m=\infty} \int d \xi_{2} v^{\prime}\left(\xi_{2}\right) \int d \xi_{2}^{\prime} v^{\prime}\left(\xi^{\prime}{ }_{2}\right) \int_{0}^{m} d x_{1} \frac{1}{\sqrt{x_{1}}} e^{-\frac{k}{x_{1}}\left(\frac{\xi_{2}-\xi^{\prime}}{2}\right)^{2}} . \tag{a}
\end{equation*}
$$

As we have:

$$
\int d \xi_{2} v^{\prime}\left(\xi_{2}\right) \int d \xi_{2}^{\prime} v^{\prime}\left(\xi_{2}^{\prime}\right) \int_{0}^{m} d x_{1} \frac{1}{\sqrt{x_{1}}}=0
$$

for all values of $m$, we may write the expression ( $\alpha$ ) also in the form:

$$
\lim _{m=\infty} \int d \xi_{2} v^{\prime}\left(\xi_{2}\right) \int d \xi_{2}^{\prime} v^{\prime}\left(\xi_{2}^{\prime}\right) \int_{0}^{m} d x_{1} \frac{1}{\sqrt{x_{1}}}\left[-1+e^{-\frac{k}{x_{1}}\left(\frac{\xi_{2}-\xi^{\prime}}{2}\right)^{2}}\right]
$$

In this form the integration with respect to $x_{1}$ is convergent; we have:

$$
\int_{0}^{\infty} d x_{1} \frac{1}{\sqrt{x_{1}}}\left[-1+e^{-\frac{k}{x_{1}}\left(\frac{\xi_{2}-\xi^{\prime}}{2}\right)^{2}}\right]=-\sqrt{\pi k} .\left|\xi_{2}-\xi_{2}^{\prime}\right| .
$$

Substituting this result in $(\beta)$, and making use of some partial integrations, we finally obtain:

$$
\begin{equation*}
\frac{\nu}{V^{2}} \iint d x_{1} d x_{2} w^{2}=\frac{1}{2 V} \int d \xi_{2} v^{2} \tag{30}
\end{equation*}
$$

Adding together the amounts given in formulae (28) and (30), we get for the full value of the integral (25):

$$
\begin{equation*}
\frac{1}{V} \iint d x_{1} d x_{2} u_{2} w=Q-\frac{1}{2 V} \int d x_{2} v^{2} \tag{31}
\end{equation*}
$$

This is exactily the opposite of the value (23), divided by $\varrho V$, which of course is necessary, as we have proved in eq. (7) that the resultant of the whole system of "interior" forces always has the value zero.

Subtracting (31) from $Q$, we obtain for the corrected value of the outflow :

$$
\begin{equation*}
Q^{\prime}=\frac{1}{2 V} \int d x_{2} v^{2} \tag{32}
\end{equation*}
$$

Hence we have:

$$
\begin{equation*}
W^{\prime}=\varrho V Q^{\prime} \tag{33}
\end{equation*}
$$

so that the accordance with the general theorem again is established.
§ 7. One final remark has to be added to the former considerations. We have seen that in order to get Zeilon's formula for the resistance the influence of the second order terms had to be taken into account. However, we have considered their influence only partly: the "interior" forces $y_{1}, y_{2}$, acting in the wake, especially those acting at distances not far from the body, will cause certain velocities at the circumference of the latter, and thus will disturb the fulfilment of the boundary conditions. So the solution is incomplete, when not a correction for this effect has been calculated, which probably will also affect the resistance.

We may summarize our considerations by saying that as soon as formula (11) is used to determine the pressure $p$, we introduce terms of the second degree in the $u_{i}$, and it becomes necessary to calculate quite a new solution.

This calculation, however, is beyond the scope of the present note; perhaps it may be the subject of a separate paper.


[^0]:    ${ }^{1}$ ) The theorem has been enunciated by various authors, see f.i. N. Filon, Proc. Roy. Soc. (A) 118, p, 7, 1926; further J. M. Burgers, Proc. Acad. Amst. 31, p. 433. 1928 and especially S. Goldstein, Proc. Roy. Soc. A 123, p. 216, 1929 and a subsequent paper by the same author, to be published soon. The present note has come out of a correspondence with Dr. GoldSTEIN on this subject.
    ${ }^{2}$ ) Comp. C. W. Oseen, Hydrodynamik (Leipzig, 1927). - The notation in the present paper is the same as that used in a former one, Proc. Acad. Amst. 32, p. 1278, 1929. The variables $u_{i}$ denote the components of the velocity of the field that by the action of the "forces" $Y_{i}$ is superposed on the general motion of the fluid with the velocity $V$ parallel to the $x_{1}$-axis.

[^1]:    ${ }^{1}$ ) N. Zeilon, K. Sv. Vet. Akad. Handl. Ser. 3, Bd. 1. 1923; C. W. Oseen, Hydrodynamik, p. 294 (the formula mentioned at p. 316 has to be corrected).
    ${ }^{2}$ ) C. W. Oseen, Hydrodynamik, p. 37. $K_{0}(x)$ is a Bessel function of the second kind, which also is denoted by $\frac{i \pi}{2} H_{0}^{\prime}(i x)$.

[^2]:    ${ }^{1}$ ) In order to justify these approximations we remark that for positive values of $x_{1}$ and for $\left|x_{2}-\xi_{2}\right|>D \sqrt{4 M x_{1} / R D}$ (or in the case of very small values of $x_{1}$, when $\left.\left|x_{2}-\xi_{2}\right|>2 M D / R\right)$ the function $\varepsilon$ vanishes as $\mathrm{e}^{-M}$. Hence, when $x_{1}$ lies below the limit mentioned in the text, we may write for any function $f\left(\xi_{2}\right)$, which is sufficiently continuous:

    $$
    \int d \xi_{2} f\left(\xi_{2}\right) \varepsilon \cong f\left(x_{2}\right) \int_{-\infty}^{+\infty} d \xi_{2} \varepsilon=\frac{2 \pi v}{V} f\left(x_{2}\right)
    $$

    Hence from all the terms containing the function $\varepsilon$ only that one has to be taken into account which is multiplied by $V / v$. For negative values of $x_{1}$ the function $\varepsilon$ vanishes very fastly.

[^3]:    1) C. W. Oseen, Hydrodynamik, p. 271. See also Proc. Acad. Amst. 31, p. 433, 1928.
[^4]:    ${ }^{1}$ ) Comp. N. Zeilon, l.e. p. 17, and C. W. Oseen, Hydrodynamik, p. 295.

[^5]:    ${ }^{1}$ ) This also applies to the back side of the body, where $X_{1}=Y_{1}, X_{2}=Y_{2}$ :

