PROJECTIVE GEOMETRIZATION OF A SYSTEM OF PARTIAL DIFFERENTIAL EQUATIONS, III: PROJECTIVE NORMAL SPACES

BY

V. HLAVATÝ

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Synopsis. This paper is a continuation of two previous papers with the same title which will be referred to as PI and PII (Kon. Ned. Akad. v. Wet., Proceedings Vol. 53, Nos 3 and 4, 1950). In the last section of PII we saw that the points **n** are not appropriate to define "projective normal spaces". In this paper we use the results of PI and PII to find a set of ("privileged") points which (together with **x**) may be used for the definition of projective normal spaces. These spaces are defined in the last section of this paper.

§ 1. Introductory notions.

Lemma (1, 1). The normal points (cf. § 4 in PI) satisfy the condition

(1, 1)
$$\mathbf{n}_{a_r...a_1} = \mathbf{n}_{(a_r...a_1)}, \quad r = 2,...,N.$$

Proof. The symbols $\left\{P_{a'r\cdots a's}^{a_s}P_{a's-1}^{a_{s-1}}a_1\right\}$ and $P_{a'r\cdots a's}^{a_s\cdots a_1}$ which appear in (1, 7) *PI* are obviously symmetric in their subscripts. If we replace in these symbols the derivatives $P_{a'q\cdots a'u}^{a_u}$ by $\Gamma_{a_u\cdots a_q}^{b_q}$ (which are symmetric in their subscripts) and the $P_{a'}^{b}$ by δ_a^{b} we obtain the symbols $\left\{\Gamma_{a_r\cdots a_s}^{b_s}\delta_{a_{s-1}\cdots a_1}^{b_{s-1}}\right\}$ and $\gamma_{a_r\cdots a_s\cdots a_1}^{b_s\cdots b_1}$, symmetric in their subscripts. Consequently the normal points defined by (4, 2) *PI* satisfy (1, 1).

Another lemma to be used later on deals with the tensor $Q_a^b = y^c \Gamma_{ac}^b$ (cf. Theorem (3, 4) in *PI*).

Lemma (1, 2). If N > 2 then

(1, 2a)
$$y^c K_{(cba)}^d = y^c K_{cba}^d - \frac{2}{3} D_{(b} Q_{a)}^d$$

and consequently if

(1, 3) $Q_a^d = Q \, \delta_a^d, \quad Q = \text{const.}$

- $(1, 4a) y^c K_{(cba)}^d = y^c K_{cba}^d$
- (1, 4b) $y^c D_{(c} \mathbf{n}_{ba} = y^c D_c \mathbf{n}_{ba}$

Proof. We have

(1, 5)
$$-y^{c} \partial_{c} \Gamma_{ab}^{d} = \Gamma_{ab}^{d}, \quad -y^{c} \partial_{a} \Gamma_{bc}^{d} = \Gamma_{ba}^{a} - \partial_{a} Q_{b}^{d}.$$

On the other hand if N > 2, then K_{cba}^{d} may be thought of as defined by (2, 3) *PII* and this equation together with (1, 5) leads at once to (1, 2a), from which (1, 4a) follows by virtue of (1, 3). Using the equation (2, 2b) in *PII*, we see that

(1, 6)
$$y^{c} D_{c} \mathbf{n}_{ba} = y^{c} \mathbf{n}_{cba} + y^{c} K_{cba}^{d} \mathbf{x}_{d}$$

(1,7)
$$y^{c} D_{(c} \mathbf{n}_{ba} = y^{c} \mathbf{n}_{(cba)} + y^{c} K_{(cba)}^{d} \mathbf{x}_{d}.$$

The equation (1, 4b) follows from (1, 6), (1, 7), (1, 1) and (1, 4a).

In the following definition we use the projective tensors K's (cf. § 1 in PII):

Definition (1, 1). A \mathfrak{P}_m will be referred to as symmetric if the following conditions hold:

I) The tensor Q_a^b satisfies the relation

$$(1, 8a) Q_a^b = Q \ \delta_a^b$$

where $Q \neq -1$ is a constant.

II) Among the tensors K's there is at least one, say $K_{a_{n+1}...a_n}^{b}$, such that

(1, 8b)
$$K \equiv K_{a_{u+1}...a_1}^{a_{u+1}} y^{a_u} ... y^{a_1} \neq 0.$$

III) If
$$N > 3$$
 then 1)

(1,9)
$$\begin{cases} a) \quad y^{a_r} D_{a_r} \mathbf{n}_{a_{r-1}\dots a_1} = y^{a_r} D_{(a_r} \mathbf{n}_{a_{r-1}\dots a_1})^{-2}) \quad (r = 4, \dots, N, \mathbf{x}_a = \mathbf{n}_a) \\ b) \quad y^{a_p} D_{a_p} D_{(a_{p-1}\dots} D_{a_{s+1}} K_{a_s\dots a_1})^{-2} = \\ \qquad y^{a_p} D_{(a_p\dots} D_{a_{s+1}} K_{a_s\dots a_1})^{-2} \quad (s = 3, 4, \dots, N-1, p = s+1, \dots, N). \end{cases}$$

Throughout this paper we will deal with symmetric cases only without stating it explicitly.

One of the consequences of (1, 8a) and (1, 9a) is stated in the following lemma where we put

(1, 10)
$$c_r \equiv N + 1 - (r-1)(Q+1), \quad r = 2, ..., N.$$

Lemma (1, 3). If $N \ge 2$, then

(1, 11*a*)
$$y^b \mathbf{n}_{ba} = y^b \mathbf{n}_{(ba)} = c_2 \mathbf{x}_a.$$

¹) The condition (1, 9a) is satisfied for r=2 and if N>2 also for r=3 (cf. the equation (1, 4b)).

²) We impose this condition in order to simplify the final results. The device used later on (cf. the equations (1, 12)) may easily be generalized for the case where (1, 9a) does not hold.

If
$$N \ge 3$$
 then
(1, 11b) $y^c \mathbf{n}_{cba} = y^c \mathbf{n}_{(cba)} = c_3 \mathbf{n}_{ba} - y^c K_{(cba)}^{\ d} \mathbf{x}_d$.
Moreover if $N \ge 4$ then
 $\begin{pmatrix} y^{a_r} \mathbf{n}_{a_r \dots a_1} = y^{a_r} \mathbf{n}_{(a_r \dots a_1)} = c_r \mathbf{n}_{a_{r-1} \dots a_1} - d_r \end{pmatrix}$

(1, 11c)
$$\left\{-\sum_{2}^{r-2} y^{a_{r}}\left\{\left\{K_{(a_{r}...a_{s}}^{b_{s}}\delta_{a_{s-1}}^{b_{s-1}}, b_{1}\right\}\right\}\mathbf{n}_{b_{s}...b_{1}}-y^{a_{r}}K_{(a_{r}...a_{1})}^{b}\mathbf{x}_{b}, r=4,...,N.\right\}$$

Proof: The first equations (1, 11) follow at once from (1, 1) and $\mathbf{n}_{ba} = \mathbf{x}_{ba} - \Gamma_{ba}^{\ c} \mathbf{x}_{c} = \mathbf{n}_{ba}$

Moreover we have by virtue of (1, 8a)

(1, 12a)
$$\begin{cases} y^{a_r} D_{a_r} \mathbf{n}_{a_{r-1}\dots a_1} = y^{a_r} [\partial_{a_r} \mathbf{n}_{a_{r-1}\dots a_1} - \Gamma_{a_{r-1}a_r} \mathbf{n}_{ha_{r-2}\dots a_1} - \dots - \Gamma_{a_1a_r} \mathbf{n}_{a_{r-1}\dots a_2h}] \\ = [N+1-(r-1)] \mathbf{n}_{a_{r-1}\dots a_1} - Q(r-1) \mathbf{n}_{a_{r-1}\dots a_1} = c_r \mathbf{n}_{a_{r-1}\dots a_1}. \\ r = 3, \dots, N \end{cases}$$

On the other hand if we use (2, 2) in PII, (1, 9a), (1, 1) and (1, 4) we obtain

$$y^{a_r} [\mathbf{n}_{a_r...a_1} - D_{a_r} \mathbf{n}_{a_{r-1}...a_1}] = y^{a_r} [\mathbf{n}_{(a_r...a_1)} - D_{(a_r} \mathbf{n}_{a_{r-1}...a_1}] =$$

$$(1, 12b) \qquad -\sum_{2}^{r-2} y^{a_r} \left\{ \left\{ K_{(a_r \dots a_s}^{b_s} \delta_{a_{s-1} \dots a_1}^{b_s}) \right\} \mathbf{n}_{b_s \dots b_1}^{3} - y^{a_r} K_{(a_r \dots a_1)}^{b} \mathbf{x}_{b} \; r = 3, \dots, N.$$

The equations (1, 11b, c) follow at once from (1, 12a, b).

Lemma (1, 4). If for each r = 2, ..., N and q' = 3, ..., N we have (1, 13) a) $c_r \neq 0$, (cf. (1, 10)) b) $\mathbf{n}_{a_q'...a_1} y^{a_1}...y^{a_p} \neq 0$, (p=2,...,q')then the osculating space $\overset{s}{P}_{m_s}{}^4$) is spanned by the points $\mathbf{n}_{a_s...a_1}$ (s=1, ..., N; $\mathbf{x}_a \equiv \mathbf{n}_a$).

Proof. The equations (4, 2) in PI show that \mathring{P}_{m_s} may be thought of as spanned by the points

(1, 14)
$$\mathbf{x}, \mathbf{x}_a \equiv \mathbf{n}_a, \dots, \mathbf{n}_{a_{s-1}\dots a_1}, \mathbf{n}_{a_s\dots a_1}$$

On the other hand **x** is a linear combination of \mathbf{n}_a , $(N+1) \mathbf{x} = y^a \mathbf{n}_a$ and if (1, 13) hold then by virtue of (1, 11) $\mathbf{n}_{a_{q-1}\dots a_1}$ is a linear combination of the points

$$\mathbf{n}_{a_q\ldots a_1}, \mathbf{n}_{a_q \ldots 2 \ldots a_i}, \ldots, \mathbf{n}_a \qquad (q = 2, \ldots, N).$$

Hence the space spanned by the points (1, 14) is identical with the space spanned by $\mathbf{n}_{a_{e}...a_{1}}$.

³) For r=3 one has to put $\sum_{2}^{r=2} = 0$. ⁴) Cf. § 1 in *PI*. 838

In the next Lemma we use (1, 8b) and put

$$H_{a_{u}} = \frac{1}{K} K_{a_{u+1}...a_{1}}^{a_{u+1}} y^{a_{u-1}}...y^{a_{1}}$$

so that we have

(1, 15) $y^a H_a = 1.$

Lemma (1, 5). The equation

(1, 16)
$$H_a^c \left(\delta_b^a + y^a H_b \right) = \delta_b^c$$

admits only one solution H_a^c . If we put

(1, 17)
$$\begin{cases} a) & H_{ab}^{\ c} \equiv 2H_{(a}H_{b)}^{\ c} = H_{(ab)}^{\ c} \\ b) & H_{a_{r+1}\dots a_{1}}^{\ c} \equiv H_{e(a_{r+1}}^{\ c}H_{a_{r}\dots a_{1}}^{\ c} = H_{(a_{r+1}\dots a_{1})}^{\ c} \qquad (r=2,\dots,N-1) \end{cases}$$

then we have

(1, 18) a)
$$y^a H_{ab}^c = \delta_b^c$$
 b) $y^{a_{r+1}} H_{a_{r+1}...a_1}^c = H_{a_{r...a_1}}^c$

Proof. The projective tensor $\delta_b^a + y^a H_b$ (homogeneous of degree 0) has obviously the rank m + 1. Hence (1, 16) admits only one solution H_a^c . On the other hand we obtain from (1, 17*a*), (1, 17*b*) for r = 2, (1, 15) and (1, 16),

(1, 19a)
$$y^{a} H_{ab}^{c} = H_{b}^{c} + H_{b} H_{a}^{c} y^{a} = H_{a}^{c} (\delta_{b}^{a} + y^{a} H_{b}) = \delta_{b}^{c}$$

 $(y^{a} H_{c})^{d} = \frac{1}{2} y^{a} (H_{c}^{d} H_{b}^{e} + H_{c}^{d} H_{c}^{e} + H_{c}^{d} H_{c}^{e})$

(1, 19b)
$$\begin{cases} 9 & H_{abc} = \frac{1}{3} \ (\delta_e^d H_{bc}^e + H_{eb}^d \delta_c^e + H_{ec}^d \delta_b^e) = H_{bc}^d \\ = \frac{1}{3} \ (\delta_e^d H_{bc}^e + H_{eb}^d \delta_c^e + H_{ec}^d \delta_b^e) = H_{bc}^d \end{cases}$$

and these equations prove (1, 18a) as well as (1, 18b) for r = 2. The remaining equations (1, 18b) may be obtained by usual induction.

§ 2. Privileged points.

Definition (2, 1). An object Ω with the components $\Omega_{a_{q}...a_{1}}^{...b...}$ will be termed a privileged object if the equation

(2, 1)
$$y^{a_s} \Omega^{\dots,b\dots}_{a_q\dots a_1} = 0$$
 $(s = 1,\dots,q)$

holds and is (x, y, g)-invariant (cf. Definition (1, 2) in PI).

Theorem (2, 1a). Let $N \geq 2$. Then

(2, 2a)
$$\frac{\mathbf{N}_{ab} = \mathbf{N}_{(ab)} = \mathbf{n}_{ab} - c_{21} H_{ab}^c \mathbf{x}_c}{(c_{21} = c_2)}$$

are privileged points,

 $(2, 3a) y^a \mathbf{N}_{ab} = y^a \mathbf{N}_{ba} = 0$

homogeneous of degree N-1

(2, 4*a*)
$$\dot{N}_{ab} = g^{(N-1)} N_{ab}$$

Proof. We have from (2, 2a) by virtue of (1, 18a) and (1, 11a)

$$y^{a} \mathbf{N}_{ab} = y^{a} \mathbf{N}_{(ab)} = (c_{2} - c_{21}) \mathbf{x}_{b}$$

and consequently if we put $c_{21} = c_2$ we have (2, 3a). This equation is obviously (x, y)-invariant. Because H_{ab}^{d} is homogeneous of degree -1, \mathbf{x}_c homogeneous of degree N and \mathbf{n}_{ab} homogeneous of degree N-1, we obtain (2, 4a). Hence (2, 3a) is also g-invariant.

Theorem (2, 1b). Let
$$N \ge 3$$
. Then (2, 2a) and
(2, 2b) $\frac{N_{cba} = N_{(cba)} = n_{cba} - c_{32} H_{(bc}^{e} \delta_{a}^{f} N_{ef} - (c_{21} c_{3} H_{(cba)}^{e} - K_{(cba)}^{e}) \mathbf{x}_{e}}{c_{32} = \frac{3 c_{3}}{2}}$

are privileged points

(2, 3b) $y^{a_s} N_{a_s a_s a_1} = 0$ s = 1, 2, 3and the points (2, 2b) are homogeneous of degree N - 2(2, 4b) $\dot{N}_{cba} = g^{(N-2)} N_{cba}$.

Proof. Let $N \ge 3$ and consider the equation

(2, 5a)
$$\mathbf{N}_{cba} = \mathbf{n}_{cba} - Q_{cba}^{de} \mathbf{N}_{de} - Q_{cba}^{d} \mathbf{x}_{d}$$

where the Q's are to be found. Using (1, 11b) and (2, 2a) we obtain

$$(2, 5b) \begin{cases} y^{c} \mathbf{N}_{cba} = c_{3} \mathbf{n}_{ba} - y^{c} K_{(cba)}^{d} \mathbf{x}_{d} - y^{c} [Q_{cba}^{de} \mathbf{N}_{de} + Q_{cba}^{d} \mathbf{x}_{d}] \\ = (c_{3} \delta_{(ba)}^{de} - y^{c} Q_{cba}^{de}) \mathbf{N}_{de} + [c_{3} c_{21} H_{ba}^{d} - y^{c} K_{(cba)}^{d} - y^{c} Q_{cba}^{d}] \mathbf{x}_{d}. \end{cases}$$

Because

$$y^{c} H_{cba}^{d} = y^{c} H_{(cba)}^{d} = H_{ba}^{d}$$

the tensor

(2, 6a)
$$Q_{cba}^{\ d} \equiv c_3 c_{21} H_{cba}^{\ d} - K_{(cba)}^{\ d} = Q_{(cba)}^{\ d}$$

reduces the last member on the right hand side to zero. On the other hand we have by virtue of (2, 3a)

$$3y^{c} H_{(cb}^{d} \delta_{a}^{e} \mathbf{N}_{de} = y^{c} (H_{cb}^{d} \delta_{a}^{e} + H_{ba}^{d} \delta_{c}^{e} + H_{ac}^{d} \delta_{b}^{e}) \mathbf{N}_{de}$$
$$= (\delta_{ba}^{de} + \delta_{ab}^{de}) \mathbf{N}_{de} = 2\delta_{(ba)}^{de} \mathbf{N}_{de}.$$

Hence the tensor

(2, 6b)
$$Q_{cba}^{de} \equiv \frac{3c_3}{2} H_{(cb}^{d} \delta_{a)}^e = Q_{(cba)}^{de}$$

reduces the first member on the right hand side of (2, 5b) to zero so that we have $y^{c} N_{cba} = 0$. This equation together with $N_{cba} = N_{(cba)}$ (which we obtain from (2, 5a) and (2, 6)) leads to (2, 3b). The remaining part of the theorem is very easily proved.

Note. If N > 3 then

$$y^d H_{dcba}^{e} = H_{cba}^{e}$$

and by virtue of (1, 8a) and (1, 9b) (used for the first time) for s = 3, p = 4

(2,7)
$$y^{d} D_{(d} K_{cba)}^{e} = y^{d} D_{d} K_{(cba)}^{e} = -2 (Q+1) K_{(cba)}^{e}.$$

Hence $Q_{cba}^{\ d}$ as defined by (2, 6a) satisfies the relation

$$(2, 8a) Q_{cba}^{\ e} = y^d P_{dcba}^{\ e}$$

where

(2, 8b)
$$P_{dcba}^{e} = P_{(dcba)}^{e} \equiv c_3 c_{21} H_{dcba}^{e} + \frac{1}{2(Q+1)} D_{(d} K_{cba)}^{e}.$$

In the next section we shall generalize this equation in order to be able to generalize the results of Theorems (2, 1).

§ 3. Auxiliary Lemma.

In the following lemma we use the abbreviations

a)
$$H_{a_u \dots a_s \dots a_1}^{b_s \dots b_1} \equiv H_{(a_u \dots a_s}^{b_s} \delta_{a_{s-1} \dots a_1}^{b_{s-1} \dots b_1 \dots b_1}$$

and

(3, 1d)
$$\begin{cases} c_{r\,r-1} \equiv \frac{rc_r}{2}, & c'_r \equiv c_r k_r, \\ r \equiv 2, \dots, N, & r \equiv 3, \dots, N \end{cases}$$

where $k_3 = 1$ and k_r for r > 3 is the number taken from the equation $(r = 4, \ldots N)$

$$\left(k_{r}y^{a_{r}}H_{a_{r}a_{r-1}a_{r-2}\ldots a_{1}}^{b_{r-2}\ldots b_{1}}-H_{a_{r-1}a_{r-2}\ldots a_{1}}^{b_{r-2}\ldots b_{1}}\right)t_{(b_{r-2}\ldots b_{1})}=0$$

which holds for any privileged tensor $t_{(b_{r-2}...b_{l})}$ whatsoever. Moreover, if $A_{...}^{...a...}$ and $B_{...}^{...a...}$ are two tensors which satisfy the equation

(3, 1e) $(A_{...}^{...a..} - B_{...}^{...a..}) t_{...a..} = 0$

for any privileged tensor $t_{\dots a\dots}$ whatsoever, then we write

Lemma (3, 1). If $N \ge 4$ and if a set of tensors Q satisfies the following conditions

$$(3,2) \qquad \begin{cases} a) \quad Q_{a_{w}a_{u-1}\dots a_{1}}^{c_{u-1}\dots c_{1}} \equiv c_{u\,u-1} H_{a_{u}a_{u-1}\dots a_{1}}^{c_{u-1}\dots c_{1}} \quad u=2,\dots,N \\ b) \quad Q_{a_{v}a_{v-1}a_{v-2}\dots a_{1}}^{c_{v-2}\dots c_{1}} \equiv c_{v-1\,v-2} c_{v}' H_{a_{v}a_{v-1}a_{v-2}\dots a_{1}}^{c_{v-2}\dots c_{1}} - k_{a_{v}a_{v-1}a_{v-2}\dots a_{1}}^{c_{v-2}\dots c_{1}} \quad v=3,\dots,N^{-6} \\ c) \quad y^{a_{w}} Q_{a_{w}\dots a_{s}\dots a_{1}}^{c_{s}\dots c_{1}} = c_{w} Q_{a_{w-1}\dots a_{s}\dots a_{1}}^{c_{s}\dots c_{1}} \\ \quad -y^{a_{w}} \left[k_{a_{w}\dots a_{s}\dots a_{1}}^{c_{s}\dots c_{1}} + \sum_{s+1}^{w-2} k_{a_{w}\dots a_{q}\dots a_{1}}^{c_{s}\dots b_{1}} Q_{b_{q}\dots b_{s}\dots b_{1}}^{c_{s}\dots c_{1}} \right]^{6} \right], \qquad w=4,\dots,N \\ s=1,2,\dots,w-3 \end{cases}$$

⁵) $H_{a_{u}...a_{1}}^{b_{1}}$ is defined by (1, 17).

⁶) For c_r cf. (1, 10).

then the equation

(3,3)
$$y^{a_w} P_{a_w \dots a_s \dots a_1} \cong Q_{a_w \dots \dots a_s \dots a_1} \quad w = 4, \dots, N; \ s = 1, \dots, w - 3$$

admits a solution $P_{a_w \dots a_s \dots a_1}^{c_s \dots c_1} = P_{(a_w \dots a_s \dots a_1)}^{c_s \dots c_1}$ homogeneous of degree s - w, which is a function of the H's, K's as well as of the derivatives up to $D_{a_w \dots} D_{a_{q+1}} k_{a_q \dots a_1}^{c_s}$ $(q = 3, \dots, w - 1)^7$) and consequently $Q_{a_w \dots a_s \dots a_1}^{c_s \dots c_1}$ satisfies the equation

(3, 2d)
$$\begin{cases} Q_{a_{w}...a_{s}...a_{1}} \cong c_{w} P_{a_{w}...a_{s}...a_{1}} - [k_{a_{w}...a_{s}...a_{1}} + k_{a_{w}...a_{s}...a_{1}} + \sum_{s+1}^{w-2} k_{a_{w}...a_{q}...a_{1}} Q_{a_{q}...b_{s}...b_{1}}] & w = 4, ..., N, \ s = 1, 2, ... w - 3. \end{cases}$$

Proof. We see from Theorems (2, 1) that the conditions (3, 2a, b) for u = 2, 3, v = 3 are satisfied ^{7a}) while (3, 2c) reduces for w = 4 to

(3.4a)
$$y^{d} Q_{dcba}^{e} = c_{4} Q_{cba}^{e} - y^{d} \left[K_{(dcba)}^{e} + c_{21} k_{dcba}^{ij} H_{ij}^{e} \right]$$

The equation (3, 3) (for w = 4) is equivalent to (2, 8a), where P is given by (2, 8b) so that we have

(3.5)
$$Q_{dcba}^{e} = c_4 \left[c_3 c_{21} H_{dcba}^{e} + \frac{1}{2 (Q+1)} D_{(d} K_{cba}^{e} \right] - (K_{(dcba)}^{e} + c_{21} k_{dcba}^{ij} H_{ij}^{e})$$

which proves our lemma for w = 4 (and s = 1 = w - 3). For the case $w = 5 \leq N$ we have to consider $Q_{a_s \dots a_1}^{b_s \dots b_1}$, s = 1, 2. The tensor $Q_{a_s \dots a_s a_t}^{b_s b_1}$, which appears in (3, 2c) for w = 5, s = 2 is given by (3, 2b) for v = 4. Because of (2, 7) and (1, 9b) we have

(3. 6a)
$$\begin{cases} y^{a_s} D_{a_s} k_{a_4 a_5 a_4 a_1} = 3 y^{a_s} D_{a_s} K_{(a_4 a_5 a_4}^{b_s} \delta_{a_1}^{b_1} = \\ \cong \frac{1_5}{4} y^{a_s} D_{(a_s} K_{a_4 a_5 a_5}^{b_3} \delta_{a_1}^{b_1} = \frac{5}{4} y^{a_s} D_{(a_s} k_{a_4 a_5 a_4}^{b_5 b_1} \end{cases}$$

 $\begin{array}{ll} (3.\ 6b) & 3\ y^{a_{\mathbf{s}}}\ D_{a_{\mathbf{s}}}\ K_{(a_{4}a_{3}a_{\mathbf{s}})}^{\ \ b_{\mathbf{s}}} = -\ 3 \cdot 2\ (1+Q)\ K_{(a_{4}a_{2}a_{\mathbf{s}})}^{\ \ b_{\mathbf{s}}}\ \delta_{a_{1}}^{b_{1}} = -\ 2\ (1+Q)\ k_{a_{4}a_{3}a_{\mathbf{s}}a_{\mathbf{s}}}^{\ \ b_{\mathbf{s}}b_{1}} \\ \text{and} \end{array}$

(3. 6c)
$$y^{a_{b}}H_{a_{b}a_{a}a_{a}a_{a}a_{a}a_{a}} \cong \frac{4}{5}H_{a_{b}a_{b}a_{a}a_{a}a_{a}}$$

Consequently

$$(3. 7a) \qquad Q_{a_{5}a_{4}a_{5}a_{4}a_{5}a_{4}a_{5}} \simeq c_{5} P_{a_{5}a_{4}a_{5}a_{5}a_{5}} - (k_{a_{5}a_{4}a_{5}a_{4}a_{5}a_{4}} + k_{a_{5}a_{4}a_{5}a_{5}a_{5}} Q_{b_{5}b_{5}b_{1}})$$

where

$$(3.7b) \quad P_{a_{s}a_{4}a_{s}a_{5}a_{1}}^{b_{s}b_{1}} = P_{(a_{s}a_{4}a_{s}a_{5}a_{1})}^{b_{s}b_{1}} = \frac{5}{4} \left[c_{32} c_{4}' H_{a_{s}a_{4}a_{5}a_{5}a_{1}}^{b_{s}b_{1}} + \frac{1}{2(1+Q)} D_{(a_{s}} k_{a_{4}a_{5}a_{4}a_{1}}^{b_{5}b_{1}} \right]$$

and these two equations prove our lemma for $w = 5 \leq N$ and s = 2. In

⁷⁾ Its construction will be given in the proof.

^{7a}) cf. the equations (2, 5) and (2, 6).

order to complete the proof for w = 5 and s = 1, we use the relationships deduced from (1, 8a) and (1, 9b)

$$y^{a_{s}} D_{(a_{s}} D_{a_{4}} K_{a_{s}a_{2}a_{1}}^{b} = y^{a_{s}} D_{a_{s}} D_{(a_{4}} K_{a_{s}a_{2}a_{1}}^{b_{1}} = -3 (1+Q) D_{(a_{4}} K_{a_{s}a_{2}a_{1}}^{b_{1}}$$
$$y^{a_{s}} D_{(a_{s}} K_{a_{4}a_{s}a_{2}a_{1}}^{b_{1}} = y^{a_{s}} D_{a_{s}} K_{(a_{4}a_{3}a_{2}a_{1})}^{b} = -3 (1+Q) K_{(a_{4}a_{3}a_{2}a_{1})}^{b_{1}}$$

so that we have by virtue of (3, 5) and (3, 6)

(3, 8a)
$$Q_{a_4a_5a_5a_1} = y^{a_5} P_{a_5\dots a_1}^{b_1}$$

where

$$(3,8b) \begin{cases} P_{a_{s}...a_{1}}^{c_{1}} = P_{(a_{s}...a_{1})}^{c_{1}} \cong c_{4} \left[c_{3} c_{21} H_{a_{s}...a_{1}}^{c_{1}} - \frac{1}{2 \cdot 3 (1+Q)^{2}} D_{(a_{s}} D_{a_{s}} K_{a_{s}a_{s}a_{1}}) \right] \\ + \left[\frac{1}{3 (Q+1)} D_{(a_{s}} K_{a_{s}...a_{1}}^{b_{1}} + \frac{5 c_{21}}{8 (1+Q)} D_{(a_{s}} k_{a_{s}a_{s}a_{s}a_{1}}) H_{c_{s}b_{1}}^{b_{1}} \right] \end{cases}$$

and consequently

(3, 8c)
$$Q_{a_{s}...a_{1}}^{c_{1}} \cong c_{5} P_{a_{s}...a_{1}}^{c_{1}} - \left(k_{a_{s}...a_{1}}^{c_{1}} + \sum_{2}^{3} k_{a_{w}...a_{q}...a_{1}}^{b_{q}...b_{1}} Q_{b_{q}...b_{1}}^{c_{1}}\right).$$

The equations (3, 8) prove the lemma for $w = 5 \leq N$, s = 1. Let us now suppose that we already proved the lemma for all $x = 4, 5, \ldots, w' < N$. Then we have in particular

(3,9)
$$Q_{a_{w'}\ldots a_{s}\ldots a_{1}}^{c_{s}\ldots c_{1}} \simeq c_{w'} P_{a_{w'}\ldots a_{s}\ldots a_{1}}^{c_{s}\ldots c_{1}} - \left[k_{a_{w'}\ldots a_{s}\ldots a_{1}}^{c_{s}\ldots c_{1}} + \sum_{s+1}^{w'-z} k_{a_{w'}\ldots a_{q}\ldots a_{1}}^{b_{q}\ldots b_{1}} Q_{b_{q}\ldots b_{s}\ldots b_{1}}^{c_{s}\ldots c_{1}} \right]$$

 $s = 1, \ldots, w'-3$

where $P_{a_{w'}\dots a_{s}\dots a_{1}}^{c_{s}\dots c_{1}} = P_{(a_{w'}\dots a_{s}\dots a_{1})}^{c_{s}\dots c_{1}}$ is a function of the *H*'s and *K*'s as well as of the derivatives up to $D_{a_{w'}\dots} D_{a_{q+1}} k_{a_{q}\dots a_{1}}^{b_{1}}$, $(q = 3, \dots, w'-1)$ and

$$(3, 10) \begin{cases} y^{a_{w'+1}} Q_{a_{w'+1}\dots a_{s}\dots a_{1}} = c_{w'+1} Q_{a_{w'}\dots a_{s}\dots a_{1}} \\ -y^{a_{w'+1}} \left[k_{a_{w'+1}\dots a_{s}\dots a_{1}} + \sum_{s+1}^{w'-1} k_{a_{w'}\dots a_{q}\dots a_{1}} Q_{b_{q}\dots b_{s}\dots b_{1}} \right] \\ s = 1, 2, \dots, w'-2. \end{cases}$$

Using now the conditions (1, 8a) and (1, 9b) we prove by the same argument as before that

(3, 11) $Q_{a_{w'}\dots a_{s}\dots a_{1}} \cong y^{a_{w'+1}} P_{a_{w'+1}\dots a_{s}\dots a_{1}} \qquad s=1,\dots,w'-3$

where $P_{a_{w'+1}\dots a_{s}\dots a_{1}}^{c_{s}\dots c_{1}} = P_{(a_{w'+1}\dots a_{s}\dots a_{1})}^{c_{s}\dots c_{1}}$ is a function of the *H*'s and *k*'s as well as of the derivatives up to $D_{a_{w'+1}\dots} D_{a_{q+1}} k_{a_{q}\dots a_{1}}$ $(q=3, \ldots w')$. Hence we have from (3, 10) and (3, 11) the equation

(3, 12)
$$\begin{cases} Q_{a_{w'+1}\dots a_{s}\dots a_{1}} \cong c_{w'+1} P_{a_{w'+1}\dots a_{s}\dots a_{1}} - \\ - \left(k_{a_{w'+1}\dots a_{s}\dots a_{1}} + \sum_{s+1}^{w'-1} k_{a_{w'+1}\dots a_{q}\dots a_{1}} Q_{b_{q}\dots b_{s}\dots b_{1}} \right) \end{cases}$$

for $s = 1, \ldots, w' - 3$. The equation (3, 12) for s = w' - 2 may be obtained by a similar argument based on (3, 2b) for v = w'. The induction based on these results proves our Lemma but for the statement of the homogeneity of the *P*'s. In order to prove this statement we observe first from (3, 2a, b) that $Q_{a_u a_{u-1} \dots a_1}^{b_{u-1} \dots b_1}$ resp. $Q_{a_u \dots a_{u-2} \dots a_1}^{b_{u-2} \dots b_1}$ is homogeneous of degree -1 resp. -2. Hence from (3, 2c) for s = w - 3 we see that $Q_{a_w \dots a_{w-3} \dots a_1}^{b_{w-3} \dots b_1}$ must be homogeneous of degree -3. Consequently, from the same equation for w = x - 1 we obtain by the same argument that $Q_{a_x \dots a_{x-4} \dots a_1}^{b_{x-4} \dots b_1}$ is homogeneous of degree -4. Proceeding in the same way we arrive at the conclusion that $Q_{a_w \dots a_s \dots a_1}^{b_s \dots b_1}$ is homogeneous of degree s - w, $(w = 4, \dots, N; s = 1, \dots, w - 3)$. Hence $P_{a_w \dots a_s \dots a_1}^{b_s \dots b_1}$ which satisfies (3, 3) must be by virtue of (3, 2d) and (3, 3) homogeneous of degree s - w.

§ 4. Privileged points. Continuation.

Lemma (3, 1) enables us to prove the following

Theorem (4, 1). Let $N \ge 4$ and let the tensors Q be defined by (3, 2a,b,c,d). Then the points

(4, 1a)
$$\begin{cases} \mathbf{N}_{a_{r}\ldots a_{1}} = \mathbf{N}_{(a_{r}\ldots a_{1})} \equiv \mathbf{n}_{a_{r}\ldots a_{1}} - \sum_{1}^{r-1} Q_{a_{r}\ldots a_{s}\ldots a_{1}} \mathbf{N}_{b_{s}\ldots b_{1}}, \\ (r = 2, \ldots, N; \mathbf{N}_{a} \equiv \mathbf{x}_{a}) \end{cases}$$

are privileged points

(4, 1b)
$$y^{a_p} \mathbf{N}_{a_r...a_1} = 0 \qquad p = 1,...,r$$

homogeneous of degree N+1-r

(4, 1c)
$$\dot{\mathbf{N}}_{a_{r}...a_{1}} = g^{(N+1-r)} \mathbf{N}_{a_{r}...a_{1}}.$$

The proof may be accomplished in four steps:

a) Theorems (2, 1) are particular cases of our theorem for r=2 resp. r=3⁸). Let us assume that we proved our Theorem for all $x=4, \ldots, r'-1, r' \leq N$.

b) Denote by $Q_{a_7,\ldots a_s\ldots a_1}^{b_s\ldots b_1}$ a set of unknown tensors and consider the points

(4, 2)
$$\mathbf{N}_{a_{r'}...a_1} \equiv \mathbf{n}_{a_{r'}...a_1} - \sum_{1}^{r'-1} Q_{a_{r'}...a_{s}...a_1} \mathbf{N}_{b_{s}...b_1}$$

⁸) For r=2 the equations (3, 2, b, c, d) do not exist. For r=3 the equations (3, 2c, d) do not exist (cf. the equation (2, 8a)).

Using Lemma (1, 3) and the equations (4, 1*a*) (where instead of r we put x = 2, 3, ..., r' - 1) we obtain from (4, 2)

$$(4,3a) \begin{cases} y^{a_{r'}} \mathbf{N}_{a_{r'\ldots a_{1}}} \equiv \left(c_{r'} \ \delta^{b_{r'-1}\ldots b_{1}}_{(a_{r'-1}\ldots a_{1})} - y^{a_{r'}} Q_{a_{r'}a_{r'-1}\ldots b_{1}}^{b_{r'-1}\ldots b_{1}}\right) \mathbf{N}_{b_{r'-1}\ldots b_{1}} \\ + \left[c_{r'} Q_{a_{r'-1}a_{r'-2}\ldots a_{1}}^{b_{r'-2}\ldots b_{1}} - y^{a_{r'}} \left(k_{a_{r'\ldots a_{r'-2}\ldots a_{1}}}^{b_{r'-2}\ldots b_{1}} + Q_{a_{r'\ldots a_{r'-2}\ldots a_{1}}}^{b_{r'-2}\ldots b_{1}}\right)\right] \mathbf{N}_{b_{r'-2}\ldots b} \\ + \sum_{i}^{r'-3} \left[c_{r'} Q_{a_{r'-1}\ldots a_{s}\ldots a_{1}}^{c_{s}\ldots c_{1}} - y^{a_{r'}} \left(Q_{a_{r'\ldots a_{s}\ldots a_{1}}}^{c_{s}\ldots c_{1}} + k_{a_{r'\ldots a_{s}\ldots a_{1}}}^{c_{s}\ldots c_{1}} + \right. \\ + \left. \sum_{s+1}^{r'-2} k_{a_{r'\ldots a_{q}\ldots a_{1}}}^{b_{q}\ldots b_{1}} Q_{b_{q}\ldots b_{s}\ldots b_{1}}^{c_{s}\ldots b_{1}}\right] \mathbf{N}_{c_{s}\ldots c_{1}}. \end{cases}$$

On the other hand we have according to (3, 1a), (1, 18b) and by virtue of (4, 1b) (for r' - 1 instead of r)

(4, 4a)
$$\begin{cases} y^{a_{r'}} H_{a_{r'}a_{r'-1}\dots a_1}^{b_{r'-1}\dots b_1} \mathbf{N}_{b_{r'-1}\dots b_1} = y^{a_{r'}} H_{(a_{r'}a_{r'-1}}^{b_{r'-1}} \delta_{a_{r'-2}\dots a_1}^{b_{r'-2}\dots b_1} \mathbf{N}_{b_{r'-1}\dots b_1} \\ = \frac{2}{r'} \delta_{(a_{r'-1}\dots a_1)}^{b_{r'-1}\dots b_1} \mathbf{N}_{b_{r'-1}\dots b_1} \end{cases}$$

and moreover according to (3, 2a) for $u = r' - 1^9$

(4, 4b)
$$\begin{cases} c_{\tau'} Q_{a_{\tau'-1}a_{\tau'-2}\dots a_1} \mathbf{N}_{b_{\tau'-2}\dots b_1} = c_{\tau'} c_{\tau'-1} \tau'-2} H_{a_{\tau'-1}a_{\tau'-2}\dots a_1} \mathbf{N}_{b_{\tau'-2}\dots b_1} \\ = c'_{\tau'} c_{\tau'-1} \tau'-2} y^{a_{\tau'}} H_{a_{\tau'}a_{\tau'-1}a_{\tau'-2}\dots a_1} \mathbf{N}_{b_{\tau'-2}\dots b_1}. \end{cases}$$

Hence if we impose on $Q_{a_r,\ldots,a_s\ldots,a_1}^{b_s\ldots,b_1}$ $(s=1,\ldots,r'-1)$ the conditions (3,2a,b,c) for u=v=w=r' then we obtain

$$(4, 3b) y^{a_{r'}} \mathbf{N}_{a_{r'} \dots a_1} = 0.$$

Moreover from (3, 2a, b, c) for u = v = w = r' we obtain (3, 2d). Hence all tensors $Q_{a_r,\ldots,a_s\ldots,a_1}^{b_s\ldots,b_1}$ are symmetric in their subscripts so that we have according to (4, 2)

$$\mathbf{N}_{a_{\tau}'\ldots a_1} = \mathbf{N}_{(a_{\tau}'\ldots a_1)}.$$

This equation together with (4, 3b) leads to

(4, 3c)
$$y^{a_p} N_{a_r,\ldots,a_1} = 0$$
 $p = 1, \ldots, r'.$

On the other hand the $Q_{a_{r'}...a_s...a_1}^{b_s...b_1}$ (s = 1, ..., r'-1) defined by (3, 2a, b, c, d) are homogeneous of degree s - r'. Hence $N_{a_{r'}...a_1}$ are homogeneous of degree N + 1 - r'.

⁹) According to our assumption in the section a) of the proof, the equation (3, 2a), resp. (3, 2b), resp. (3, 2c, d) exist for u = 2, ..., r' - 1, resp. v = 3, ..., r' - 1, resp. w = 4, ..., r' - 1.

c) Starting with Theorems (2, 1) and applying the same arguments as in b), we easily prove the statements of our theorems for all $x = 4, \ldots$ $\cdots r' - 1$. Hence the assumption of section a) is fulfilled.

d) The usual induction based on the assumption of the section a) and on the results of section b) proves our theorem for r = 2, ..., N.

§ 5. Projective normal spaces.

Definition (5, 1). The space spanned by the points \mathbf{x} , $\mathbf{N}_{a_r...a_1}$ will be denoted by $\overset{r-1}{N_{n_r-1}}$ and referred to as the (r-1)st projective normal space of our \mathfrak{P}_m , $(r=2,\ldots,N)$.

Theorem (5, 1). The normal space $N_{n_{r-1}}$ has the following properties a) It is (x, y, g)-invariant.

b) It is contained in the osculating space P_{m_r} and intersects P_{m_s} (s < r) only in **x**.

c) If

(5, 1) a)
$$c_2 c_3 \dots c_r \neq 0$$
, b) $\mathbf{n}_{a_q \dots a_1} y^{a_1} \dots y^{a_p} \neq 0$,
 $q = 3, \dots, r; p = 2, \dots, r$

then its dimension is

 $(5, 2) n_{r-1} = m_r - m_{r-1}.$

Proof. Because the points **x**, $N_{a_{r...a_1}}$ are (x, y)-invariant, $N_{n_{r-1}}^{-1}$ is obviously (x, y)-invariant. Because **x**, $N_{a_{r...a_1}}$ are homogeneous (of degree N+1 resp. N+1-r) the space spanned by them must be g-invariant.

On the other hand using (4, 1a) as well as the equations (4, 2) in PI we see that $N_{a_r...a_1}$ may be expressed in the following way

(5,3)
$$\mathbf{N}_{a_{r}\ldots a_{1}} \equiv \mathbf{x}_{a_{r}\ldots a_{1}} + \sum_{1}^{r-1} \mathcal{Q}_{a_{r}\ldots a_{s}\ldots a_{1}}^{b_{s}\ldots b_{1}} \mathbf{x}_{b_{s}\ldots b_{1}}$$

Hence all points $\mathbf{N}_{a_r...a_1}$ are in $\overset{r}{P}_{m_r}$ and consequently $\overset{r}{N}_{n_{r-1}}^{-1} \subset \overset{r}{P}_{m_r}$. Moreover if some point $\mathbf{P} \neq \mathbf{x}$ of $\overset{r-1}{N}_{n_{r-1}}$ is in $\overset{q}{P}_{m_q}$ (q < r) then according to (5, 3) it must be a linear combination of points $y^{a_r} ... y^{a_{q+1}} \mathbf{N}_{a_r...a_1}$. Because $\mathbf{N}_{a_r...a_1} \equiv \mathbf{N}_{(a_r...a_1)}$ are privileged points, we have

$$y^{a_r} \dots y^{a_{q+1}} \, \mathbf{N}_{a_r \dots a_1} = 0$$

and consequently there is no point $\mathbf{P} \neq \mathbf{x}$ of $N_{n_{r-1}}^{r-1}$ in $P_{m_q}^{q}$ (q < r). Consider now the equations

(5, 4)
$$\begin{cases} a) & \mathbf{n}_{a_{r}\ldots a_{1}} = \mathbf{N}_{a_{r}\ldots a_{1}} + \mathbf{M}_{a_{r}\ldots a_{1}} \\ b) & \mathbf{M}_{a_{r}\ldots a_{1}} \equiv \sum_{1}^{r-1} Q_{a_{r}\ldots a_{s}\ldots a_{1}}^{b_{s}\ldots b_{1}} \mathbf{N}_{b_{s}\ldots b_{1}}, \qquad (\mathbf{N}_{a} \equiv \mathbf{x}_{a}) \end{cases}$$

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(equivalent with (4, 1*a*)) and denote by $\overset{r-1}{P'_{m_{r-1}}} \subset \overset{r-1}{P}_{m_{r-1}}^{1}$ the space spanned by the points **x**, $\mathbf{M}_{a_{r}...a_{1}}$. Suppose $m'_{r-1} < m_{r-1}$. Since $\overset{r-1}{N}_{n_{r-1}}^{1}$ intersects $\overset{q}{P}_{m_{q}}$ (q < r) only in **x**, the space spanned by the points $\mathbf{n}_{a_{r}...a_{1}}$, which satisfy (5, 4*a*), can not be $\overset{r}{P}_{m_{r}}$ for $m'_{r-1} < m_{r-1}$ and this together with (5, 1) contradicts Lemma (1, 4). Because we can not have $m'_{r-1} > m_{r-1}$ and the assumption $m'_{r-1} < m_{r-1}$ is a contradictory one, we must have

 $m'_{r-1} = m_{r-1}$, so that the space spanned by the points **x**, $\mathbf{M}_{a_r...a_1}$ is the osculating space $P_{m_{r-1}}^{-1}$. Hence we see from (5, 4*a*) and from the statement *b*) that (5, 2) holds.

Note: The points $N_{(a_r...a_i)}$ (r = 2, ..., N) which (together with **x**) span the normal space $N_{n_{r-1}}$ are linearly dependent even in the maximal case (cf. equation (4, 1b)):

Theorem (5, 2). In the maximal case the points $\mathbf{N}_{(a_r...a_1)}$ are linearly "interdependent", e.g. any of their linear combination which is equal to zero must be built up as a linear combination of $y^{a_p} \mathbf{N}_{a_m.a_1}$ (p = 1, ..., r).

Proof. Introduce a special parameter system for which $y^a = \delta_o^a$ at P. Then (5, 3) reduces to

(5,5)
$$\mathbf{N}_{(a_r...a_1)} = \mathbf{x}_{(a_r...a_1)} + \sum_{1}^{r-1} \Omega_{(a_r...a_{s}...a_1)} \mathbf{x}_{b_{s...b_1}} \text{ at } P$$

 $(a_1,...,a_r = 1,...,m)$

while the remaining equations (5, 3) reduce to identity 0 = 0. In order to prove our theorem, it is sufficient to prove that $\mathbf{N}_{(a_r...a_i)}$ are linearly independent: The points $\mathbf{x}_{(a_r...a_i)}$ span $\overset{r}{P}_{m_r}$ while the points $\mathbf{x}_{(a_roo...oa_{s-1}...a_i)}$ span $\overset{s}{P}_{m_s}$. Hence in the maximal case [where the points $\mathbf{x}_{(a_r...a_i)}$ are linearly independent] the points $\mathbf{x}_{(a_r...a_i)}$ are linearly independent and span (together with \mathbf{x}) a n_{r-1} -dimensional space ¹⁰) $M_{n_{r-1}} \subset \overset{r}{P}_{m_r}$ not contained in $\overset{r}{P}_{m_{r-1}}^{-1}$. Consequently by virtue of (5, 5) the points $\mathbf{N}_{(a_r...a_i)}$ are linearly independent.

Note. Suppose m = 1. Because $y^a \mathbf{x}_a = (N+1)\mathbf{x}$, the points \mathbf{x}_0 , \mathbf{x}_1 are on the tangential line (the first osculating space $\overset{1}{P}_1$) of \mathfrak{P}_1 at \mathbf{x} . Introduce a parameter system y^a for which $y^a = \delta_0^a$ at \mathbf{x} . Then we have in this parameter system

$$0 = y^a \operatorname{N}_{ab} = \operatorname{N}_{ob}$$
 at **x**.

¹⁰)
$$n_{r-1} = \binom{m+r-1}{r} = \binom{m+r}{r} - \binom{m+r-1}{r-1} = m_r - m_{r-1}.$$

Hence the set of points N_{ab} reduces here to N_{11} and the space $\overset{1}{N_1}$ spanned by x, N_{ab} is the line which joins the points x and N_{11} (the first projective normal). Because $\overset{1}{N_1}$ is y-invariant it does not depend on the choice of parameters. Hence if we chose again an arbitrary parameter system, we obtain the same straight line $\overset{1}{N_1}$ which contains the points x, N_{ab} . It may be easily proved by the same argument that the space $\overset{r-1}{N_{n_{r-1}}}$ is a straight line (the (r-1)st projective normal) which contains the points x, $N_{a_r...a_1}$ (r=2, ..., N).

> Indiana University Department of Mathematics

Bloomington (Indiana), U.S.A.