## MATHEMATICS

## PROJECTIVE GEOMETRIZATION OF A SYSTEM OF PARTIAL DIFFERENTIAL EQUATIONS, III: PROJECTIVE <br> NORMAL SPACES

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Synopsis. This paper is a continuation of two previous papers with the same title which will be referred to as $P I$ and $P I I$ (Kon. Ned. Akad. v. Wet., Proceedings Vol. 53, Nos 3 and 4, 1950). In the last section of $P I I$ we saw that the points $\mathbf{n}$ are not appropriate to define "projective normal spaces". In this paper we use the results of PI and PII to find a set of ("privileged") points which (together with $\mathbf{x}$ ) may be used for the definition of projective normal spaces. These spaces are defined in the last section of this paper.

## § 1. Introductory notions.

Lemma (1, 1). The normal points (cf. § 4 in PI) satisfy the condition

$$
\begin{equation*}
\mathbf{n}_{a_{r} \ldots a_{1}}=\mathbf{n}_{\left(a_{r} \ldots a_{1}\right)}, \quad r=2, \ldots, N \tag{1,1}
\end{equation*}
$$

 appear in $(1,7) P I$ are obviously symmetric in their subscripts. If we replace in these symbols the derivatives $P_{a^{\prime}{ }_{q} \ldots a^{\prime} u}^{a_{u}}$ by $\Gamma_{a_{u} \ldots a_{q}}{ }^{b_{q}}$ (which are symmetric in their subscripts) and the $P_{a}^{b}$, by $\delta_{a}^{b}$ we obtain the symbols $\left\{\Gamma_{a_{r} \ldots a_{s}}^{b_{s}} \delta_{a_{s-1} \ldots a_{1}}^{b_{s-1} \ldots b_{1}}\right\}$, $\gamma_{a_{r} \ldots a_{s} \ldots a_{1}}$, symmetric in their subscripts. Consequently the normal points defined by (4, 2) PI satisfy (1, 1).

Another lemma to be used later on deals with the tensor $Q_{a}^{b}=y^{c} \Gamma_{a c}^{b}$ (cf. Theorem (3, 4) in PI).

Lemma (1, 2). If $N>2$ then

$$
\begin{equation*}
y^{c} K_{(c b a)}^{d}=y^{c} K_{c b a}^{d}-\frac{2}{3} D_{(b} Q_{a)}^{d} \tag{1,2a}
\end{equation*}
$$

and consequently if

$$
\begin{equation*}
Q_{a}^{d}=Q \delta_{a}^{d}, \quad Q=\text { const. } \tag{1,3}
\end{equation*}
$$

then

| $(1,4 a)$ | $y^{c} K_{(c b a)}^{d}=y^{c} K_{c b a}^{d}$ |
| :--- | :--- |
| $(1,4 b)$ | $y^{c} D_{(c} \mathbf{n}_{b a)}=y^{c} D_{c} \mathbf{n}_{b a}$ |

Proof. We have
$(1,5)$

$$
-y^{c} \partial_{c} \Gamma_{a b}^{d}=\Gamma_{a b}^{d}, \quad-y^{c} \partial_{a} \Gamma_{b c}^{d}=\Gamma_{b a}^{a}-\partial_{a} Q_{b}^{d}
$$

On the other hand if $N>2$, then $K_{c b a}^{d}$ may be thought of as defined by $(2,3) P I I$ and this equation together with $(1,5)$ leads at once to $(1,2 a)$, from which ( $1,4 a$ ) follows by virtue of ( 1,3 ). Using the equation ( $2,2 b$ ) in PII, we see that

$$
\begin{equation*}
y^{c} D_{c} \mathbf{n}_{b a}=y^{c} \mathbf{n}_{c b a}+y^{c} K_{c b a}^{d} \mathbf{x}_{d} \tag{1,6}
\end{equation*}
$$

$$
\begin{equation*}
y^{c} D_{(c} \mathbf{n}_{b a)}=y^{c} \mathbf{n}_{(c b a)}+y^{c} K_{(c b a)}^{d} \mathbf{x}_{d} \tag{1,7}
\end{equation*}
$$

The equation ( $1,4 b$ ) follows from ( 1,6 ), $(1,7),(1,1)$ and $(1,4 a)$.
In the following definition we use the projective tensors $K$ 's (cf. § 1 in PII):

Definition (1, 1). A $\mathfrak{\Re}_{m}$ will be referred to as symmetric if the following conditions hold:
I) The tensor $Q_{a}^{b}$ satisfies the relation

$$
\begin{equation*}
Q_{a}^{b}=Q \delta_{a}^{b} \tag{1,8a}
\end{equation*}
$$

where $Q \neq-1$ is a constant.
II) Among the tensors $K$ 's there is at least one, say $K_{a_{u+1} \ldots a_{1}}$, such that

$$
\begin{equation*}
K \equiv K_{a_{u+1} \ldots a_{1}} y^{a_{u+1}} \ldots y^{a_{u}} \neq 0 \tag{1,8b}
\end{equation*}
$$

III) If $N>3$ then ${ }^{1}$ )

$$
\begin{cases}\text { a) } & \left.y^{a_{r}} D_{a_{r}} \mathbf{n}_{a_{r-1} \ldots a_{1}}=y^{a_{r}} D_{\left(a_{r}\right.} \mathbf{n}_{\left.a_{r-1} \ldots a_{1}\right)}{ }^{2}\right) \quad\left(r=4, \ldots, N, \mathbf{x}_{a}=\mathbf{n}_{a}\right)  \tag{1,9}\\ b) & y^{a_{p}} D_{a_{p}} D_{\left(a_{p-1} \ldots\right.} D_{a_{s+1}} K_{\left.a_{g} \ldots a_{1}\right)}^{c}= \\ & y^{a_{p}} D_{\left(a_{p} \ldots\right.} D_{a_{s+1}} K_{\left.a_{s \ldots} \ldots a_{1}\right)}^{c} \quad(s=3,4, \ldots, N-1, p=s+1, \ldots, N)\end{cases}
$$

Throughout this paper we will deal with symmetric cases only without stating it explicitly.
One of the consequences of ( $1,8 a$ ) and ( $1,9 a$ ) is stated in the following lemma where we put

$$
\begin{equation*}
c_{r} \equiv N+1-(r-1)(Q+1), \quad r=2, \ldots, N \tag{1,10}
\end{equation*}
$$

Lemma (1,3). If $N \geqq 2$, then

$$
\begin{equation*}
y^{b} \mathbf{n}_{b a}=y^{b} \mathbf{n}_{(b a)}=c_{2} \mathbf{x}_{a} \tag{1,11a}
\end{equation*}
$$

[^0]
## If $N \geqq 3$ then

$$
\begin{equation*}
y^{c} \mathbf{n}_{c b a}=y^{c} \mathbf{n}_{(c b a)}=c_{3} \mathbf{n}_{b a}-y^{c} K_{(c b a)}^{d} \mathbf{x}_{d} . \tag{1,11b}
\end{equation*}
$$

Moreover if $N \geqq 4$ then

Proof: The first equations (1, 11) follow at once from ( 1,1 ) and

$$
\mathbf{n}_{b a}=\mathbf{x}_{b a}-\Gamma_{b a}^{c} \mathbf{x}_{c}=\mathbf{n}_{b a}
$$

Moreover we have by virtue of ( $1,8 a$ )

$$
\left\{\begin{array}{c}
y^{a_{r}} D_{a_{r}} \mathbf{n}_{a_{r-1} \ldots a_{1}}=y^{a_{r}\left[\partial_{a_{r}} \mathbf{n}_{a_{r-1} \ldots a_{1}}-\Gamma_{a_{r-1} a_{r}} \mathbf{n}_{h a_{r-2} \ldots a_{1}}-\ldots-\Gamma_{a_{1} a_{r}}^{h} \mathbf{n}_{a_{r-1} \ldots a_{2} h}\right]}  \tag{1,12a}\\
=[N+\mathbf{1}-(r-1)] \mathbf{n}_{a_{r-1} \ldots a_{1}} Q(r-1) \mathbf{n}_{a_{r-1} \ldots a_{1}}=c_{r} \mathbf{n}_{a_{r-1} \ldots a_{1}} \\
r=3, \ldots, N
\end{array}\right.
$$

On the other hand if we use $(2,2)$ in $P I I,(1,9 a),(1,1)$ and $(1,4)$ we obtain

$$
y^{a_{r}}\left[\mathbf{n}_{a_{r} \ldots a_{1}}-D_{a_{r}} \mathbf{n}_{a_{r-1} \ldots a_{1}}\right]=y^{a_{r}}\left[\mathbf{n}_{\left(a_{r} \ldots a_{1}\right)}-D_{\left(a_{r}\right.} \mathbf{n}_{a_{r-1} \ldots a_{1}}\right]=
$$

$$
\begin{equation*}
\left.-\sum_{2}^{r-2} y^{a_{r}}\left\{\left\{K_{\left(a_{r} \ldots a_{8}\right.}^{b_{s}} \delta_{\left.a_{s-1} \ldots a_{1}\right)}^{b_{s}-1} b_{1}^{b_{1}}\right)\right\} \mathbf{n}_{b_{g} \ldots b_{1}}{ }^{3}\right)-y^{a_{r}} K_{\left(a_{r} \ldots a_{1}\right)}^{\stackrel{b}{x_{b}}} \quad r=3, \ldots, N \tag{1,12b}
\end{equation*}
$$

The equations ( $1,11 b, c$ ) follow at once from ( $1,12 a, b$ ).
Lemma (1, 4). If for each $r=2, \ldots, N$ and $q^{\prime}=3, \ldots, N$ we have
a) $\quad c_{r} \neq 0$, (cf. $\left.(1,10)\right)$
b) $\mathbf{n}_{a_{q}, \ldots a_{1}} y^{a_{1}} \ldots y^{a_{p}} \neq 0, \quad\left(p=2, \ldots, q^{\prime}\right)$
then the osculating space $\left.\stackrel{s}{P_{m_{s}}}{ }^{4}\right)$ is spanned by the points $\mathbf{n}_{a_{g} \ldots a_{1}}(s=1, \ldots, N$; $\mathbf{x}_{a} \equiv \mathbf{n a}_{a}$ ).

Proof. The equations (4, 2) in $P I$ show that $\stackrel{8}{P}_{m_{s}}$ may be thought of as spanned by the points

$$
\begin{equation*}
\mathbf{x}, \mathbf{x}_{a} \equiv \mathbf{n}_{a}, \ldots, \mathbf{n}_{a_{s-1} \ldots a_{1}}, \mathbf{n}_{a_{s} \ldots a_{1}} \tag{1,14}
\end{equation*}
$$

On the other hand $\mathbf{x}$ is a linear combination of $\mathbf{n}_{a},(N+1) \mathbf{x}=y^{a} \mathbf{n}_{a}$ and if $(1,13)$ hold then by virtue of $(1,11) \mathbf{n}_{a_{q-1} \ldots a_{1}}$ is a linear combination of the points

$$
\mathbf{n}_{a_{q} \cdots a_{1}}, \mathbf{n}_{a_{q-2} \cdots a_{1}}, \ldots, \mathbf{n}_{a} \quad(q=2, \ldots, N)
$$

Hence the space spanned by the points $(1,14)$ is identical with the space spanned by $\mathbf{n}_{a_{s} \ldots a_{1}}$.
${ }^{3}$ ) For $r=3$ one has to put $\sum_{\frac{s}{r-2}}^{r-} \equiv 0$.
$\left.{ }^{4}\right)$ Cf. $\S 1$ in $P I$.

In the next Lemma we use $(1,8 b)$ and put

$$
H_{a_{u}} \equiv \frac{1}{K} K_{a_{u+1} \ldots a_{1}}^{a_{u+1}} y^{a_{u-1}} \ldots y^{a_{1}}
$$

so that we have

$$
\begin{equation*}
y^{a} H_{a}=1 \tag{1,15}
\end{equation*}
$$

Lemma (1,5). The equation

$$
\begin{equation*}
H_{a}^{c}\left(\delta_{b}^{a}+y^{a} H_{b}\right)=\delta_{b}^{c} \tag{1,16}
\end{equation*}
$$

admits only one solution $H_{a}^{c}$. If we put

$$
\begin{cases}a) & H_{a b}^{c} \equiv 2 H_{(a} H_{b)}^{c}=H_{(a b)}^{c}  \tag{1,17}\\ b) \quad H_{a_{r+1} \ldots a_{1}}^{c} \equiv H_{e\left(a_{r+1}\right.}^{c} H_{\left.a_{r} \ldots a_{1}\right)}^{e}=H_{\left(a_{r+1} \cdots a_{1}\right)}^{c} \quad(r=2, \ldots, N-1)\end{cases}
$$

then we have
a) $y^{a} H_{a b}^{c}=\delta_{b}^{c}$
b) $y^{a_{r+1}} H_{a_{r+1} \ldots a_{1}}=H_{a_{r} \ldots a_{1}}$.

Proof. The projective tensor $\delta_{b}^{a}+y^{a} H_{b}$ (homogeneous of degree 0) has obviously the rank $m+1$. Hence $(1,16)$ admits only one solution $H_{a}^{c}$. On the other hand we obtain from ( $1,17 a$ ), $(1,17 b)$ for $r=2$, $(1,15)$ and ( 1,16 ),

$$
\begin{equation*}
y^{a} H_{a b}^{c}=H_{b}^{c}+H_{b} H_{a}^{c} y^{a}=H_{a}^{c}\left(\delta_{b}^{a}+y^{a} H_{b}\right)=\delta_{b}^{c} \tag{1,19a}
\end{equation*}
$$

$$
\left\{\begin{align*}
y^{a} H_{a b c}^{d} & =\frac{1}{3} y^{a}\left(H_{e a}^{d} H_{b c}^{e}+H_{e b}^{d} H_{c a}^{e}+H_{e c}^{d} H_{a b}^{e}\right)  \tag{1,19b}\\
& =\frac{1}{3}\left(\delta_{e}^{d} H_{b c}^{e}+H_{e b}^{d} \delta_{c}^{e}+H_{e c}^{d} \delta_{b}^{e}\right)=H_{b c}^{d}
\end{align*}\right.
$$

and these equations prove $(1,18 a)$ as well as $(1,18 b)$ for $r=2$. The remaining equations ( $1,18 b$ ) may be obtained by usual induction.

## § 2. Privileged points.

Definition (2, 1). An object $\Omega$ with the components $\Omega_{a_{q} \ldots a_{1}}^{\ldots b . \ldots}$ will be termed a privileged object if the equation

$$
\begin{equation*}
y^{a_{s}} \Omega_{a_{q} \ldots a_{1}}^{\ldots b \ldots}=0 \quad(s=1, \ldots, q) \tag{2,1}
\end{equation*}
$$

holds and is $(x, y, g)$-invariant (cf. Definition (1, 2) in PI).
Theorem $(2,1 a)$. Let $N \geqq 2$. Then

$$
\begin{equation*}
\frac{\mathbf{N}_{a b}=\mathbf{N}_{(a b)}=\mathbf{n}_{a b}-c_{21} H_{a b}^{c} \mathbf{x}_{c}}{\left(c_{21}=c_{2}\right)} \tag{2,2a}
\end{equation*}
$$

are privileged points,

$$
\begin{equation*}
y^{a} \mathbf{N}_{a b}=y^{a} \mathbf{N}_{b a}=0 \tag{2,3a}
\end{equation*}
$$

homogeneous of degree $N-1$
(2, 4a)

$$
\dot{\mathbf{N}}_{a b}=g^{(N-1)} \mathbf{N}_{a b}
$$

Proof. We have from ( $2,2 a$ ) by virtue of ( $1,18 a$ ) and ( $1,11 a$ )

$$
y^{a} \mathbf{N}_{a b}=y^{a} \mathbf{N}_{(a b)}=\left(c_{\mathbf{2}}-c_{21}\right) \mathbf{x}_{b}
$$

and consequently if we put $c_{21}=c_{2}$ we have ( $2,3 a$ ). This equation is obviously $(x, y)$-invariant. Because $H_{a b}^{d}$ is homogeneous of degree -1, $\mathbf{x}_{c}$ homogeneous of degree $N$ and $\mathbf{n}_{a b}$ homogeneous of degree $N-1$, we obtain $(2,4 a)$. Hence $(2,3 a)$ is also $g$-invariant.

Theorem $(2,1 b)$. Let $N \geqq 3$. Then $(2,2 a)$ and

$$
(2,2 b) \frac{\mathbf{N}_{c b a}=\mathbf{N}_{(c b a)}=\mathbf{n}_{c b a}-c_{32} H_{(b c}^{e} \delta_{a)}^{\prime} \mathbf{N}_{e f}-\left(c_{21} c_{3} H_{(c b a)}^{e}-K_{(c b a)}^{e}\right) \mathbf{x}_{e}}{c_{32}=\frac{3 c_{3}}{2}}
$$

are privileged points

$$
(2,3 b)
$$

$$
y^{a_{s}} \mathbf{N}_{a_{3} a_{2} a_{1}}=0 \quad s=1,2,3
$$

and the points $(2,2 b)$ are homogeneous of degree $N-2$

$$
\begin{equation*}
\dot{\mathbf{N}}_{c b a}=g^{(N-2)} \mathbf{N}_{c b a} . \tag{2,4b}
\end{equation*}
$$

Proof. Let $N \geqq 3$ and consider the equation

$$
\begin{equation*}
\mathbf{N}_{c b a}=\mathbf{n}_{c b a}-Q_{c b a}^{d e} \mathbf{N}_{d e}-Q_{c b a}^{d} \mathbf{x}_{d} \tag{2,5a}
\end{equation*}
$$

where the $Q$ 's are to be found. Using $(1,11 b)$ and $(2,2 a)$ we obtain

$$
(2,5 b)\left\{\begin{aligned}
y^{c} \mathbf{N}_{c b a} & =c_{3} \mathbf{n}_{b a}-y^{c} K_{(c b a)}^{d} \mathbf{x}_{d}-y^{c}\left[Q_{c b a}^{d e} \mathbf{N}_{d e}+Q_{c b a}^{d} \mathbf{x}_{d}\right] \\
& =\left(c_{3} \delta_{(b a)}^{d e}-y^{c} Q_{c b a}^{d e}\right) \mathbf{N}_{d e}+\left[c_{3} c_{21} H_{b a}^{d}-y^{c} K_{(c b a)}^{d}-y^{c} Q_{c b a}^{d}\right] \mathbf{x}_{d} .
\end{aligned}\right.
$$

Because

$$
y^{c} H_{c b a}^{d}=y^{c} H_{(c b a)}^{d}=H_{b a}^{d}
$$

the tensor

$$
\begin{equation*}
Q_{c b a}^{d} \equiv c_{3} c_{21} H_{c b a}^{d}-K_{(c b a)}^{d}=Q_{(c b a)}^{d} \tag{2,6a}
\end{equation*}
$$

reduces the last member on the right hand side to zero. On the other hand we have by virtue of ( $2,3 a$ )

$$
\begin{aligned}
3 y^{c} H_{(c b}^{d} \delta_{a)}^{e} \mathbf{N}_{d e} & =y^{c}\left(H_{c b}^{d} \delta_{a}^{e}+H_{b a}^{d} \delta_{c}^{e}+H_{a c}^{d} \delta_{b}^{e}\right) \mathbf{N}_{d e} \\
& =\left(\delta_{b a}^{d e}+\delta_{a b}^{d e}\right) \mathbf{N}_{d e}=\mathbf{2} \delta_{(b a)}^{d e} \mathbf{N}_{d e}
\end{aligned}
$$

Hence the tensor

$$
\begin{equation*}
Q_{c b a}^{d e} \equiv \frac{3 c_{3}}{2} H_{(c b}^{d} \delta_{a)}^{e}=Q_{(c b a)}^{d e} \tag{2,6b}
\end{equation*}
$$

reduces the first member on the right hand side of $(2,5 b)$ to zero so that we have $y^{c} \mathbf{N}_{c b a}=0$. This equation together with $\mathbf{N}_{c b a}=\mathbf{N}_{(c b a)}$ (which we obtain from ( $2,5 a$ ) and ( 2,6 )) leads to ( $2,3 b$ ). The remaining part of the theorem is very easily proved.

Note. If $N>3$ then

$$
y^{d} H_{d c b a}^{e}=H_{c b a}^{e}
$$

and by virtue of $(1,8 a)$ and $(1,9 b)$ (used for the first time) for $s=3, p=4$

$$
\begin{equation*}
y^{d} D_{(d} K_{c b a)}^{e}=y^{d} D_{d} K_{(c b a)}^{e}=-2(Q+1) K_{(c b a)}^{e} . \tag{2,7}
\end{equation*}
$$

Hence $Q_{c b a}{ }^{d}$ as defined by ( $2,6 a$ ) satisfies the relation

$$
\begin{equation*}
Q_{c b a}^{e}=y^{d} P_{a c b a}^{e} \tag{2,8a}
\end{equation*}
$$

where

$$
\begin{equation*}
P_{d c b a}^{e}=P_{(d c b a)}^{e} \equiv c_{3} c_{21} H_{d c b a}^{e}+\frac{1}{2(Q+1)} D_{(d} K_{c b a)}^{e} . \tag{2,8b}
\end{equation*}
$$

In the next section we shall generalize this equation in order to be able to generalize the results of Theorems (2, 1).

## § 3. Auxiliary Lemma.

In the following lemma we use the abbreviations

$$
\begin{align*}
& \text { a) } \left.\quad H_{a_{l} \cdots a_{g} \ldots a_{1}}{ }^{b_{g} \ldots b_{1}} \equiv H_{\left(a_{l} \ldots a_{s}\right.}{ }^{b_{s}} \delta_{\left.a_{g-1} \ldots a_{1}\right)}^{b_{s-1}}{ }^{b_{s-1} \ldots b_{1}}{ }^{5}\right) \\
& \text { b) } \quad k_{a_{u+1} \ldots a_{s} \ldots a_{1}}=\left\{\left\{K_{\left(a_{u+1} \ldots a_{s}\right.}{ }_{b_{s} \ldots b_{1}}^{b_{s}} \delta_{\left.a_{g-1} \ldots a_{1}\right)}^{b_{s-1} \ldots b_{1}}\right)\right\}  \tag{3,1}\\
& \text { c) } \quad k_{a_{u+1} \ldots a_{1}} \stackrel{b_{1}}{b_{1}} \equiv K_{\left(a_{u+1} \ldots a_{1}\right)}{ }^{b_{1}} \\
& (u=2, \ldots, N ; s=2, \ldots, u-1)
\end{align*}
$$

and

$$
\begin{cases}c_{r r-1} \equiv{\frac{r c_{r}}{2}}^{6}, & c_{r}^{\prime} \equiv c_{r} k_{r}  \tag{3,1d}\\ r=2, \ldots, N & r=3, \ldots, N\end{cases}
$$

where $k_{3}=1$ and $k_{r}$ for $r>3$ is the number taken from the equation $(r=4, \ldots N)$

$$
\left(k_{r} y^{a_{r}} H_{a_{r} a_{r-1} a_{r-2} \ldots a_{1}}^{b_{r-2} \ldots b_{1}}-H_{a_{r-1} a_{r-2} \ldots a_{1}}^{b_{r-2} \ldots b_{1}}\right) t_{\left(b_{r-2} \ldots b_{1}\right)}=0
$$

which holds for any privileged tensor $t_{\left(b_{r-2} \ldots b_{1}\right)}$ whatsoever. Moreover, if $A_{\ldots}^{\ldots \ldots}$ and $B_{\ldots}^{\ldots \ldots}$ are two tensors which satisfy the equation

$$
\begin{equation*}
\left(A_{\ldots}^{\ldots a \ldots}-B_{\ldots \ldots}^{\ldots \ldots}\right) t_{\ldots . . . . .}=0 \tag{3,1e}
\end{equation*}
$$

for any privileged tensor $t_{\ldots \ldots \ldots}$ whatsoever, then we write

$$
\begin{equation*}
A_{\ldots}^{\ldots a \ldots} \cong B_{\ldots}^{\ldots a \ldots} \tag{3,1f}
\end{equation*}
$$

Lemma (3, 1). If $N \geqq 4$ and if a set of tensors $Q$ satisfies the following conditions
$(3,2)$

$$
\begin{aligned}
& \text { (a) } \\
& Q_{a_{u} a_{u-1} \cdots a_{1}}^{c_{u-1} \ldots c_{1}} \equiv c_{u u-1} H_{a_{u} a_{u-1} \cdots a_{1}}{ }^{c_{u-1} \ldots c_{1}} \quad u=2, \ldots, N
\end{aligned}
$$

$\left.{ }^{5}\right) \quad H_{a_{u} \ldots a_{1}}{ }^{b_{1}}$ is defined by $(1,17)$.
$\left.{ }^{6}\right)$ For $c_{r}$ cf. $(1,10)$.
then the equation

$$
y^{a_{w}} P_{a_{w} \ldots a_{s} \ldots a_{1}} \begin{gather*}
c_{g} \ldots c_{1} \tag{3,3}
\end{gather*} Q_{a_{w-1} \ldots a_{s} \ldots a_{1}}^{c_{g} \ldots c_{1}} \quad w=4, \ldots, N ; s=1, \ldots, w-3
$$

admits a solution $P_{a_{w} \ldots a_{s} \ldots a_{1}}^{c_{s} \ldots c_{1}}=P_{\left(a_{w} \ldots a_{g} \ldots a_{1}\right)} \begin{gathered}c_{1} \ldots\end{gathered}$ homogeneous of degree $s-w$, which is a function of the $H$ 's, $K$ 's as well as of the derivatives up to $\left.D_{a_{w} \ldots . .} D_{a_{q+1}} k_{a_{q} \ldots . . a_{1}}^{c}(q=3, \ldots, w-1)^{7}\right)$ and consequently $Q_{a_{w} \ldots a_{g} \ldots a_{1}}^{c_{g} \ldots c_{1}}$ satisfies the equation

Proof. We see from Theorems (2,1) that the conditions (3, 2a,b) for $u=2,3, v=3$ are satisfied ${ }^{7 a}$ ) while ( $3,2 c$ ) reduces for $w=4$ to

$$
\begin{equation*}
y^{d} Q_{d c b a}^{e}=c_{4} Q_{c b a}^{e}-y^{d}\left[K_{(d c b a)}^{e}+c_{21} k_{d c b a}^{i j} H_{i j}^{e}\right] \tag{4a}
\end{equation*}
$$

The equation $(3,3)$ (for $w=4$ ) is equivalent to $(2,8 a)$, where $P$ is given by $(2,8 b)$ so that we have

$$
\begin{equation*}
Q_{d c b a}^{e}=c_{4}\left[c_{3} c_{21} H_{d c b a}^{e}+\frac{1}{2(Q+1)} D_{(d} K_{c b a)}^{e}\right]-\left(K_{(d c b a)}^{e}+c_{21} k_{d c b a}^{i j} H_{i j}^{e}\right) \tag{3.5}
\end{equation*}
$$ which proves our lemma for $w=4$ (and $s=1=w-3$ ). For the case $w=5 \leqq N$ we have to consider $Q_{a_{s} \ldots a_{1}}^{b_{g} \ldots b_{1}}, s=1,2$. The tensor $Q_{a_{4} \ldots a_{2} a_{1}}^{\substack{b_{1} b_{1}}}$ which appears in $(3,2 c)$ for $w=5, s=2$ is given by $(3,2 b)$ for $v=4$. Because of $(2,7)$ and $(1,9 b)$ we have

(3. 6b) $3 y^{a_{s}} D_{a_{4}} K_{\left(a_{4} a_{3} a_{2}\right.}^{b_{2}} \delta_{\left.a_{1}\right)}^{b_{1}}=-3.2(1+Q) K_{\left(a_{4} a_{2} a_{2}\right.}^{b_{2}} \delta_{\left.a_{1}\right)}^{b_{1}}=-2(1+Q) k_{a_{4} a_{1} a_{1} a_{1}}^{b_{1} b_{1}}$ and

$$
\begin{equation*}
y^{a_{5}} H_{a_{5} a_{4} a_{3} a_{2} a_{1}}^{b_{1}, b_{1}} \simeq \frac{4}{5} H_{a_{4} a_{3} a_{2} a_{1}}^{\substack{b_{1}, \\ \hline}} \tag{3.6c}
\end{equation*}
$$

Consequently
where

$$
\begin{equation*}
P_{a_{5} a_{4} a_{3} a_{3} a_{2} a_{1}}^{b_{1} b_{1}}=P_{\left(a_{5} a_{4} a_{3} a_{2} a_{2} a_{1}\right)}^{b_{2} b_{1}}=\frac{5}{4}\left[c_{32} c_{4}^{\prime} H_{a_{3} a_{4} a_{3} a_{2} a_{1}}^{b_{1} b_{1}}+\frac{1}{2(1+Q)} D_{\left(a_{3}\right.} k_{a_{4} a_{4} a_{4} a_{2} a_{1}}^{b_{1} b_{1}}\right] \tag{3.7b}
\end{equation*}
$$

and these two equations prove our lemma for $w=5 \leqq N$ and $s=2$. In

[^1]order to complete the proof for $w=5$ and $s=1$, we use the relationships deduced from ( $1,8 a$ ) and ( $1,9 b$ )
\[

$$
\begin{aligned}
& y^{a_{5}} D_{\left(a_{6}\right.} D_{a_{4}} K_{\left.a_{5} a_{3} a_{1}\right)}^{b}=y^{a_{5}} D_{a_{4}} D_{\left(a_{6}\right.} K_{\left.a_{4} a_{2} a_{1}\right)}^{b_{1}}=-3(1+Q) D_{\left(a_{4}\right.} K_{\left.a_{a}, a_{4} a_{1}\right)}^{b_{1}} \\
& y^{a_{5}} D_{\left(a_{6}\right.} K_{\left.a, a_{4} a_{3} a_{1} a_{1}\right)}^{b_{1}}=y^{a_{5}} D_{a_{5}} K_{\left(a_{4} a_{5} a_{2} a_{1}\right)}^{b}=-3(1+Q) K_{\left(a_{4} a_{0} a_{3} a_{1}\right)}^{b_{1}}
\end{aligned}
$$
\]

so that we have by virtue of $(3,5)$ and $(3,6)$

$$
\begin{equation*}
Q_{a_{4} a_{0} b_{2} a_{1}}^{b_{1}}=y^{a_{6}} P_{a_{6} \ldots a_{1}}{ }^{b_{1}} \tag{3,8a}
\end{equation*}
$$

where
and consequently

$$
\begin{equation*}
Q_{a_{s} \ldots a_{1}}^{\stackrel{c_{1}}{1}} \cong c_{5} P_{a_{5} \ldots a_{1}}-\left(k_{a_{5} \ldots a_{1}} \stackrel{c_{1}}{c_{1}}+\sum_{2}^{3} k_{a_{w} \ldots a_{a} \ldots a_{1}}^{\stackrel{b_{q} \ldots b_{1}}{ }} Q_{b_{q} \ldots b_{1}}^{c_{1}}\right) . \tag{3,8c}
\end{equation*}
$$

The equations $(3,8)$ prove the lemma for $w=5 \leqq N, s=1$. Let us now suppose that we already proved the lemma for all $x=4,5, \ldots, w^{\prime}<N$. Then we have in particular

$$
\begin{align*}
& s=1, \ldots, w^{\prime}-3 \tag{3,9}
\end{align*}
$$

where $P_{a_{w^{\prime}} \ldots a_{s} \ldots a_{1}}^{c_{g} \ldots c_{1}}=P_{\left(a_{w^{\prime}}, \ldots a_{g} \ldots a_{1}\right)}{ }^{c_{g}, \ldots a_{1}}$ is a function of the $H^{\prime}$ 's and $K$ 's as well as of the derivatives up to $D_{a_{w^{\prime}} \ldots} D_{a_{q+1}} k_{a_{q} \ldots a_{1}}^{\stackrel{b_{1}}{2}},\left(q=3, \ldots, w^{\prime}-1\right)$ and

Using now the conditions $(1,8 a)$ and $(1,9 b)$ we prove by the same argument as before that

$$
\begin{equation*}
Q_{a_{w^{\prime}}, \ldots a_{s} \ldots a_{1}}^{c_{g} \ldots c_{1}} \cong y^{a_{w^{\prime}+1}} P_{a_{w^{\prime}+1} \ldots a_{s} \ldots a_{1}}^{c_{s} \ldots c_{1}} \quad s=1, \ldots, w^{\prime}-3 \tag{3,11}
\end{equation*}
$$

where $P_{a_{w^{\prime}+1} \ldots a_{g} \ldots a_{1}}=P_{\left(a_{w^{\prime}+1} \ldots a_{g} \ldots a_{1}\right)}{ }^{c_{g} \ldots c_{1}}$ is a function of the $H$ 's and $k$ 's as well as of the derivatives up to $D_{a_{w^{\prime}+1} \ldots} D_{a_{q+1}} k_{a_{q \ldots} \ldots a_{1}}\left(q=3, \ldots w^{\prime}\right)$. Hence we have from $(3,10)$ and $(3,11)$ the equation

$$
\left\{\begin{array}{l}
\left.Q_{a_{w^{\prime}+1} \ldots a_{3} \ldots a_{1}}^{b_{g} \ldots b_{1}} \cong c_{w^{\prime}+1} P_{a_{w^{\prime}+1} \ldots a_{s} \ldots a_{1}} \begin{array}{l}
c_{1} \ldots c_{1} \\
-\left(k_{a_{w^{\prime}+1} \ldots a_{s} \ldots a_{1}}^{c_{s} \ldots c_{1}}+\sum_{s+1}^{w^{\prime}} k_{a_{w^{\prime}+1} \ldots a_{q} \ldots a_{1}}^{{ }_{b_{1} \ldots b_{1}}} Q_{b_{q} \ldots b_{1} \ldots b_{1}}^{c_{g} \ldots c_{1}}\right.
\end{array}\right) \tag{3,12}
\end{array}\right.
$$

for $s=1, \ldots, w^{\prime}-3$. The equation $(3,12)$ for $s=w^{\prime}-2$ may be obtained by a similar argument based on $(3,2 b)$ for $v=w^{\prime}$. The induction based on these results proves our Lemma but for the statement of the homogeneity of the $P$ 's. In order to prove this statement we observe first from (3,2a,b) that $Q_{a_{u} a_{u-1} \ldots a_{1}}^{b_{u-1} \cdots b_{1}}$ resp. $Q_{a_{u} \cdots a_{u-2} \ldots a_{1}}^{b_{u-2} \ldots b_{1}}$ is homogeneous of degree - 1 resp. - 2. Hence from $(3,2 c)$ for $s=w-3$ we see that $Q_{a_{w} \cdots a_{w-3} \ldots a_{1}}^{b_{w-3} \ldots b_{1}}$ must be homogeneous of degree - 3. Consequently, from the same equation for $w=x-1$ we obtain by the same argument that $Q_{a_{x} \ldots a_{x=4} \ldots a_{1}}^{b_{x-4} \ldots b_{1}}$ is homogeneous of degree - 4. Proceeding in the same way we arrive at the conclusion that $Q_{a_{w} \ldots . . a_{s} \ldots a_{1}}^{b_{s} \ldots b_{1}}$ is homogeneous of degree $s-w,(w=4, \ldots, N ; s=1, \ldots w-3)$. Hence $P_{a_{w} \ldots a_{g} \ldots a_{1}}^{b_{g} \ldots b_{1}}$ which satisfies $(3,3)$ must be by virtue of $(3,2 d)$ and $(3,3)$ homogeneous of degree $s-w$.

## § 4. Privileged points. Continuation.

Lemma (3, 1) enables us to prove the following
Theorem $(4,1)$. Let $N \geqq 4$ and let the tensors $Q$ be defined by $(3,2 a, b, c, d)$. Then the points

$$
\left\{\begin{array}{c}
\mathbf{N}_{a_{r} \ldots a_{1}}=\mathbf{N}_{\left(a_{r} \ldots a_{1}\right)} \equiv \mathbf{n}_{a_{r} \ldots a_{1}}-\sum_{1}^{r-1} Q_{a_{r} \ldots a_{s \ldots} \ldots a_{1}}^{b_{s \ldots b_{1}}^{b_{1}}} \mathbf{N}_{b_{s} \ldots b_{1}},  \tag{4,1a}\\
\left(r=2, \ldots, N ; \mathbf{N}_{a} \equiv \mathbf{x}_{a}\right)
\end{array}\right.
$$

are privileged points

$$
\begin{equation*}
y^{a_{p}} \mathbf{N}_{a_{r} \ldots a_{1}}=0 \quad p=1, \ldots, r \tag{4,1b}
\end{equation*}
$$

homogeneous of degree $N+1-r$

$$
\begin{equation*}
\dot{\mathbf{N}}_{a_{r} \ldots a_{1}}=g^{(N+1-r)} \mathbf{N}_{a_{r} \ldots a_{1}} \tag{4,1c}
\end{equation*}
$$

The proof may be accomplished in four steps:
a) Theorems $(2,1)$ are particular cases of our theorem for $r=2$ resp. $r=3^{8}$ ). Let us assume that we proved our Theorem for all $x=4, \ldots, r^{\prime}-1, r^{\prime} \leqq N$.
b) Denote by $Q_{a_{r}, \ldots a_{s} \ldots a_{1}}^{b_{s} \ldots b_{1}}$ a set of unknown tensors and consider the points

$$
\begin{equation*}
\mathbf{N}_{a_{r^{\prime}} \ldots a_{1}} \equiv \mathbf{n}_{a_{r} \ldots a_{1}}-\sum_{1}^{r^{\prime}-1} Q_{a_{r^{\prime} \ldots a_{s} \ldots a_{1}}^{b_{s} \ldots b_{1}}}^{b_{b_{s} \ldots b_{1}}} \tag{4,2}
\end{equation*}
$$

[^2]Using Lemma $(1,3)$ and the equations $(4,1 a)$ (where instead of $r$ we put $\left.x=2,3, \ldots, r^{\prime}-1\right)$ we obtain from $(4,2)$

On the other hand we have according to $(3,1 a),(1,18 b)$ and by virtue of ( $4,1 b$ ) (for $r^{\prime}-1$ instead of $r$ )

and moreover according to (3,2a) for $u=r^{\prime}-1^{9}$ )

Hence if we impose on $Q_{a_{r^{\prime}} \ldots a_{g^{\prime} \ldots a_{1}}} \begin{gathered}b_{g^{\prime}} . . b_{1} \\ g_{1}\end{gathered}\left(s=1, \ldots, r^{\prime}-1\right)$ the conditions $(3,2 a, b, c)$ for $u=v=w=r^{\prime}$ then we obtain

$$
\begin{equation*}
y^{a_{\tau^{\prime}}} \mathbf{N}_{a_{r^{\prime}} \ldots a_{1}}=0 . \tag{4,3b}
\end{equation*}
$$

Moreover from (3, 2a, b, c) for $u=v=w=r^{\prime}$ we obtain (3, 2d). Hence all tensors $Q_{a_{r} \prime \ldots a_{g} \ldots a_{1}} \begin{gathered}b_{g}, . . b_{1} \\ \text { are }\end{gathered}$ symmetric in their subscripts so that we have according to $(4,2)$

$$
\mathbf{N}_{a_{r^{\prime} \ldots a_{1}}}=\mathbf{N}_{\left(a_{\gamma^{\prime} \ldots a_{1}}\right)} .
$$

This equation together with $(4,3 b)$ leads to

$$
\begin{equation*}
y^{a_{p}} \mathbf{N}_{a_{r^{\prime}} \ldots a_{1}}=0 \quad p=1, \ldots, r^{\prime} \tag{4,3c}
\end{equation*}
$$

On the other hand the $Q_{a_{r^{\prime}} \ldots a_{g} \ldots a_{1}} \begin{gathered}b_{g} \ldots b_{1} \\ \left(s=1, \ldots, r^{\prime}-1\right) \text { defined by }(3,2 a, b, c, d) ~\end{gathered}$ are homogeneous of degree $s-r^{\prime}$. Hence $\mathbf{N}_{a_{\tau^{\prime}} \ldots a_{1}}$ are homogeneous of degree $N+1-r^{\prime}$.

[^3]c) Starting with Theorems (2,1) and applying the same arguments as in $b$ ), we easily prove the statements of our theorems for all $x=4, \ldots$ $\ldots r^{\prime}-1$. Hence the assumption of section $a$ ) is fulfilled.
d) The usual induction based on the assumption of the section a) and on the results of section $b$ ) proves our theorem for $r=2, \ldots, N$.

## § 5. Projective normal spaces.

Definition (5,1). The space spanned by the points $\mathbf{x}, \mathbf{N}_{a_{r} . . a_{1}}$ will be denoted by $\stackrel{r-1}{N_{n}}$ and referred to as the $(r-1)$ st projective normal space of our $\mathfrak{P}_{m},(r=2, \ldots, N)$.

Theorem (5, 1). The normal space $\stackrel{r-1}{N}_{n_{r-1}}$ has the following properties
a) It is $(x, y, g)$-invariant.
b) It is contained in the osculating space $\stackrel{r}{P}_{m_{r}}$ and intersects $\stackrel{s}{P}_{m_{s}}(s<r)$ only in $\mathbf{x}$.
c) $I f$

$$
\begin{aligned}
(5,1) \quad \text { a) } \quad c_{2} c_{3} \ldots c_{r} & \neq 0, \quad \text { b) } \quad \mathbf{n}_{a_{q} \ldots a_{1}} y^{a_{1}} \ldots y^{a_{p}} \neq 0 \\
q & =3, \ldots, r ; p=2, \ldots, r
\end{aligned}
$$

then its dimension is

$$
\begin{equation*}
n_{r-1}=m_{r}-m_{r-1} . \tag{5,2}
\end{equation*}
$$

Proof. Because the points $\mathbf{x}, \mathbf{N}_{a_{r} \ldots a_{1}}$ are $(x, y)$-invariant, $\stackrel{r-1}{N_{n_{r-1}}^{1}}$ is obviously $(x, y)$-invariant. Because $\mathbf{x}, \mathbf{N}_{a_{r} \ldots a_{1}}$ are homogeneous (of degree $N+1$ resp. $N+1-r$ ) the space spanned by them must be $g$-invariant.

On the other hand using $(4,1 a)$ as well as the equations $(4,2)$ in $P I$ we see that $\mathbf{N}_{a_{r} \ldots a_{1}}$ may be expressed in the following way

$$
\begin{equation*}
\mathbf{N}_{a_{r} \ldots a_{1}} \equiv \mathbf{x}_{a_{r} \ldots a_{1}}+\sum_{1}^{r-1} \Omega_{a_{r} \ldots a_{s} \ldots a_{1}}^{b_{s} \ldots b_{1}} \mathbf{x}_{b_{s} \ldots b_{1}} \tag{5,3}
\end{equation*}
$$

Hence all points $\mathbf{N}_{a_{r} \ldots a_{1}}$ are in $\stackrel{r}{P}_{m_{r}}$ and consequently $\stackrel{r}{N}_{n_{r-1}}^{\mathbf{1}} \subset \stackrel{r}{P}_{m_{r}}$. Moreover if some point $\mathbf{P} \neq \mathbf{x}$ of $\stackrel{r-1}{N_{n_{r-1}}}$ is in $\stackrel{q}{P}_{m_{q}}(q<r)$ then according to $(5,3)$ it must be a linear combination of points $y^{a_{r}} \ldots y^{a_{a+1}} \mathbf{N}_{a_{r} . . a_{1}}$. Because $\mathbf{N}_{a_{r} \ldots a_{1}} \equiv \mathbf{N}_{\left(a_{r} \ldots a_{1}\right)}$ are privileged points, we have

$$
y^{a_{r}} \ldots y^{a_{a+1}} \mathbf{N}_{a_{r} \ldots a_{1}}=0
$$

and consequently there is no point $\mathbf{P} \neq \mathbf{x}$ of $\stackrel{r}{N}_{n_{r-1}}^{1}$ in $\stackrel{g}{P}_{m_{\boldsymbol{q}}}(q<r)$. Consider now the equations
$(5,4) \quad \begin{cases}a) & \mathbf{n}_{a_{r} \ldots a_{1}}=\mathbf{N}_{a_{r} \ldots a_{1}}+\mathbf{M}_{a_{r} \ldots a_{1}} \\ \text { b) } & \mathbf{M}_{a_{r \ldots a}} \equiv \sum_{1}^{r s} Q_{a_{r} \ldots a_{s} \ldots a_{1}}^{b_{s} \ldots b_{1}} \mathbf{N}_{b_{s} \ldots b_{1}}, \quad\left(\mathbf{N}_{a} \equiv \mathbf{x}_{a}\right)\end{cases}$
(equivalent with (4, $1 a$ )) and denote by $\stackrel{r}{P}_{m_{r-1}^{\prime}}^{1} C^{\Gamma} \bar{P}_{m_{r-1}}^{1}$ the space spanned by the points $\mathbf{x}, \mathbf{M}_{a_{r} \ldots . a_{1}}$. Suppose $m_{r-1}^{\prime}<m_{r-1}$. Since $\stackrel{r}{N}_{n_{r-1}}^{1}$ intersects $\stackrel{q}{P}_{m_{q}}(q<r)$ only in $\mathbf{x}$, the space spanned by the points $\mathbf{n}_{a_{r} \ldots a_{1}}$, which satisfy ( $5,4 a$ ), can not be $\stackrel{r}{P}_{m_{r}}$ for $m_{r-1}^{\prime}<m_{r-1}$ and this together with $(5,1)$ contradicts Lemma ( 1,4 ). Because we can not have $m_{r-1}^{\prime}>m_{r-1}$ and the assumption $m_{r-1}^{\prime}<m_{r-1}$ is a contradictory one, we must have $m_{r-1}^{\prime}=m_{r-1}$, so that the space spanned by the points $\mathbf{x}, \mathbf{M}_{a_{r} \ldots a_{1}}$ is the osculating space ${ }^{\stackrel{r}{P}}{ }_{m_{r-1}}$. Hence we see from $(5,4 a)$ and from the statement b) that $(5,2)$ holds.

Note: The points $\mathbf{N}_{\left(a_{r} \ldots a_{1}\right)}(r=2, \ldots, N)$ which (together with $\mathbf{x}$ ) span the normal space ${ }^{r} \bar{N}_{n_{r-1}}^{1}$ are linearly dependent even in the maximal case (cf. equation ( $4,1 b$ )):

Theorem (5, 2). In the maximal case the points $\mathbf{N}_{\left(a_{r} \ldots a_{1}\right)}$ are linearly "interdependent", e.g. any of their linear combination which is equal to zero must be built up as a linear combination of $y^{a_{p}} \mathbf{N}_{a_{r} \ldots a_{1}}(p=1, \ldots, r)$.

Proof. Introduce a special parameter system for which $y^{a}=\delta_{o}^{a}$ at $P$. Then (5, 3) reduces to

$$
\begin{gather*}
\mathbf{N}_{\left(a_{r} \ldots a_{1}\right)}=\mathbf{x}_{\left(a_{r} \ldots a_{1}\right)}+\sum_{1}^{r-1} \Omega_{\left(a_{r} \ldots a_{g} \ldots a_{1}\right)}^{b_{s} \ldots b_{1}} \mathbf{x}_{b_{1} \ldots b_{1}} \text { at } P  \tag{5,5}\\
\left(\alpha_{1}, \ldots, a_{r}=1, \ldots, m\right)
\end{gather*}
$$

while the remaining equations $(5,3)$ reduce to identity $0=0$. In order to prove our theorem, it is sufficient to prove that $\mathbf{N}_{\left(a_{r} \ldots a_{1}\right)}$ are linearly independent: The points $\mathbf{x}_{\left(a_{r} \ldots a_{1}\right)}$ span $\stackrel{\tau}{P}_{m_{r}}$ while the points $\mathbf{x}_{\left(a_{r} o \ldots \ldots o a_{s-1} \ldots a_{1}\right)}$ span $\stackrel{s}{P}_{m_{s}}$. Hence in the maximal case [where the points $\mathbf{x}_{\left(a_{r} \ldots a_{1}\right)}$ are linearly independent] the points $\mathbf{x}_{\left(a_{r} \ldots a_{1}\right)}$ are linearly independent and span (together with $\mathbf{x}$ ) a $n_{r-1}$-dimensional space ${ }^{10}$ ) $M_{n_{r-1}} \subset \stackrel{r}{P_{m_{r}}}$ not contained in ${ }^{r} \bar{P}_{m_{r-1}}^{1}$. Consequently by virtue of $(5,5)$ the points $\mathbf{N}_{\left(a_{r} \ldots a_{1}\right)}$ are linearly independent.

Note. Suppose $m=1$. Because $y^{a} \mathbf{x}_{a}=(N+1) \mathbf{x}$, the points $\mathbf{x}_{0}, \mathbf{x}_{1}$ are on the tangential line (the first osculating space $\stackrel{1}{P}_{1}$ ) of $\mathfrak{P}_{1}$ at $\mathbf{x}$. Introduce a parameter system $y^{a}$ for which $y^{a}=\delta_{0}^{a}$ at $\mathbf{x}$. Then we have in this parameter system

$$
0=y^{a} \mathbf{N}_{a b}=\mathbf{N}_{o b} \text { at } \mathbf{x}
$$

10) $\quad n_{r-1}=\binom{m+r-1}{r}=\binom{m+r}{r}-\binom{m+r-1}{r-1}=m_{r}-m_{r-1}$.

Hence the set of points $\mathbf{N}_{a b}$ reduces here to $\mathbf{N}_{11}$ and the space $\stackrel{1}{N}_{1}$ spanned by $\mathbf{x}, \mathbf{N}_{a b}$ is the line which joins the points $\mathbf{x}$ and $\mathbf{N}_{11}$ (the first projective normal). Because $\stackrel{1}{N}_{1}$ is $y$-invariant it does not depend on the choice of parameters. Hence if we chose again an arbitrary parameter system, we obtain the same straight line $\stackrel{1}{N}_{1}$ which contains the points $\mathbf{x}, \mathbf{N}_{a b}$. It may be easily proved by the same argument that the space $\stackrel{r-1}{N}_{n_{r-1}}^{1}$ is a straight line (the ( $r-1$ )st projective normal) which contains the points $\mathbf{x}, \mathbf{N}_{a_{r} \ldots a_{1}}(r=2, \ldots N)$.

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[^0]:    ${ }^{1}$ ) The condition ( $1,9 a$ ) is satisfied for $r=2$ and if $N>2$ also for $r=3$ (cf. the equation ( $1,4 b$ )).
    ${ }^{2}$ ) We impose this condition in order to simplify the final results. The device used later on (cf. the equations (1.12)) may easily be generalized for the case where ( $1,9 a$ ) does not hold.

[^1]:    ${ }^{7}$ ) Its construction will be given in the proof.
    ${ }^{7 a}$ ) cf. the equations $(2,5)$ and $(2,6)$.

[^2]:    ${ }^{8}$ ) For $r=2$ the equations (3, 2, b, c, d) do not exist. For $r=3$ the equations $(3,2 c, d)$ do not exist (cf. the equation ( $2,8 a)$ ).

[^3]:    ${ }^{9}$ ) According to our assumption in the section $a$ ) of the proof, the equation (3, 2a), resp. (3, $2 b$ ), resp. ( $3,2 c, d$ ) exist for $u=2, \ldots, r^{\prime}-1$, resp. $v=3, \ldots, r^{\prime}-1$, resp. $w=4, \ldots, r^{\prime}-1$.

